## Lecture 5

COT4210 DISCRETE STRUCTURES
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PORTIONS FROM SIPSER, INTRODUCTION TO THE THEORY OF COMPUTATION, 3 RD ED., 2013

## Revisited: NFA-to-DFA Conversion

NFAs have three capabilities that DFAs don't:

- Multiple transitions on the same symbol
- Empty-string transitions
- No transitions on some symbols


# Revisited: NFA-to-DFA Conversion: Multiple Transitions 

Recall our original NFA


## Revisited: NFA-to-DFA Conversion: Multiple Transitions



Recall our original NFA
Now recall what computation on it looks like

- Every time we have more than one choice, we spin off as many copies of the NFA as necessary to account for that choice


## Revisited: NFA-to-DFA Conversion: Multiple Transitions



Recall our original NFA
Now recall what computation on it looks like

- Every time we have more than one choice, we spin off as many copies of the NFA as necessary to account for that choice

Observe that we only need the copies that are actually unique against time and current states

- We only care whether we accept or not, not how many times we accept
- At a given time, it only matters whether we are in a given state or not - not how many times we are in it
- This means prior computation doesn't matter


## Revisited: NFA-to-DFA Conversion: Empty Transitions



Multiple transitions imply that at any given time, an NFA is in a set of states

What about empty transitions?

- Note that the empty string never appears here


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- ...but everywhere $q_{2}$ does, $q_{3}$ does too


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What about empty transitions?

- Note that the empty string never appears here
- ...but everywhere $q_{2}$ does, $q_{3}$ does too
- We can handle empty-string transitions by just "looking forward" at them and including them in the set of possible states at a given moment

Empty transitions are handled in computation by including their possibilities in the set of states

## Revisited: NFA-to-DFA Conversion: Empty Transitions



Multiple transitions imply that at any given time, an NFA is in a set of states

Empty transitions are handled in computation by including their possibilities in the set of states

What about missing transitions?

- We're already in a set of states
- If a state in that set is missing a transition from our next input symbol, it just doesn't add anything to the next set of states

Missing transitions simply don't add anything to the next set of states

## Revisited: NFA-to-DFA Conversion: Simulating the NFA

Keep in mind our three observations about the computation process of an NFA:

1. Multiple transitions imply that at any given time, an NFA is in a set of states
2. Empty transitions are handled in computation by including their possibilities in the set of states
3. Missing transitions simply don't add anything to the next set of states

Now take this a bit further:

- The power set $P(Q)$ of an NFA's states is the set of all possible subsets of its states
- So at any given time, the set of states an NFA is in is an element in $P(Q)$
- $P(Q)$ is itself a set

So on a given transition, an NFA is simply transitioning from one element of $P(Q)$ to another

## Revisited: NFA-to-DFA Conversion: Simulating the NFA

Keep in mind our three observations about the computation process of an NFA:

1. Multiple transitions imply that at any given time, an NFA is in a set of states
2. Empty transitions are handled in computation by including their possibilities in the set of states
3. Missing transitions simply don't add anything to the next set of states

We have also observed that:
4. On a given transition, an NFA is simply transitioning from one element of $P(Q)$ to another

Now consider empty and missing transitions:

- The possibilities of empty transitions are included in the set of states by look-ahead
- Missing transitions are handled by simply not adding anything to the set of states
- So given the next input symbol, we account for them completely in the next set of states

This means that an NFA transitions from one element of $P(Q)$ to another element of $P(Q)$ based only on the next input symbol

## Revisited: NFA-to-DFA Conversion: Simulating the NFA

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1. Multiple transitions imply that at any given time, an NFA is in a set of states
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We have also observed that:
4. On a given transition, an NFA is simply transitioning from one element of $P(Q)$ to another
5. An NFA transitions from one element of $P(Q)$ to another element of $P(Q)$ based only on the next input symbol

So while an NFA is computing, we have:

- A finite set of states it can be in, and
- A way to know which state it will be in next, given only its current state and the input symbol


## Revisited: NFA-to-DFA Conversion: Simulating the NFA

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## Building the DFA



We want to build a DFA $D=\left\{Q_{D}, \Sigma, \delta_{D}, q_{D D}, F_{D}\right\}$ that simulates NFA $N=\left\{Q_{N}, \Sigma, \delta_{N}, q_{0 N}, F_{N}\right\}$

We need to figure out:

- The state set
- The transition function
- The start state
- The final states


## Building the DFA: States



We want to build a DFA $D=\left\{Q_{D}, \Sigma, \delta_{D}, q_{D D}, F_{D}\right\}$ that simulates NFA $N=\left\{Q_{N}, \Sigma, \delta_{N}, q_{0 N}, F_{N}\right\}$

The state set is the easiest part: just remember that we need to simulate being in some subset of the states of $N$, and say:

- $Q_{D}=P\left(Q_{N}\right)$, the power set of $Q_{N}$


## Building the DFA: Starting



We want to build a DFA $D=\left\{Q_{D}, \Sigma, \delta_{D}, q_{0 D}, F_{D}\right\}$ that simulates NFA $N=\left\{Q_{N}, \Sigma, \delta_{N}, q_{0 N}, F_{N}\right\}$

- $Q_{D}=\mathrm{P}\left(Q_{N}\right)$, the power set of $Q_{N}$

Next let's look at the start state

- Easy answer: the state corresponding to being in, and only in, the start state of the NFA
- ...with one wrinkle: empty-string transitions

So we need the set-state containing:

- $q_{0 N}$
- The states you can reach from $q_{0 N}$ with only empty-string transitions

Let's call that set-state $\mathrm{E}\left(\left\{q_{0 N}\right\}\right)$, and say:

- $q_{O D}=\mathrm{E}\left(\left\{q_{O N}\right\}\right)$


## Building the DFA: Acceptance



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We want to build a DFA $D=\left\{Q_{D}, \Sigma, \delta_{D}, q_{0 D}, F_{D}\right\}$ that simulates NFA $N=\left\{Q_{N}, \Sigma, \delta_{N}, q_{0 N}, F_{N}\right\}$

- $Q_{D}=P\left(Q_{N}\right)$, the power set of $Q_{N}$
- $q_{O D}=E\left(\left\{q_{0 N}\right\}\right)$

Next the accept states - which actually are easy

- Recall that the NFA accepts if it has any computation path to an accept state
- This means that in our computation, if there is any state we could be in that is an NFA accept state, we accept

So a state-set accepts if it contains any accept state from the NFA

$$
\begin{aligned}
& \text { - } F_{D}=\left\{R \in Q_{D} \mid R \text { and } F_{N} \text { have a common member }\right\} \text {, or } \\
& \text { - } F_{D}=\left\{R \in Q_{D} \mid R \cap F_{N} \neq \varnothing\right\}
\end{aligned}
$$

## Building the DFA: Transition



We want to build a DFA $D=\left\{Q_{D}, \Sigma, \delta_{D}, q_{D D}, F_{D}\right\}$ that simulates NFA $N=\left\{Q_{N}, \Sigma, \delta_{N}, q_{0 N}, F_{N}\right\}$

- $Q_{D}=P\left(Q_{N}\right)$, the power set of $Q_{N}$
- $q_{0 D}=E\left(\left\{q_{0 N}\right\}\right)$
- $F_{D}=\left\{R \in Q_{D} \mid R \cap F_{N} \neq \varnothing\right\}$

Now the transition function. Remember:

- The NFA transitions between sets of states
- We simulate that by having a state for each possible set

So to transition on a given symbol $a$, we:

- Look at all the NFA states we are currently simulating
- Look at all the states they can possibly transition to on a
- Transition to the set of all of those states


## Building the DFA: Transition



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- Look at all the NFA states we are currently simulating
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- Transition to the set of all of those states

So we define $\delta_{D}: Q_{D} \times \Sigma \rightarrow Q_{D}$ as:

- $\delta_{D}(R, a)=\left\{q \in Q_{N} \mid q \in \delta_{N}(r, a)\right.$ for some $\left.r \in R\right\}$
- ...almost


## Building the DFA: Transition



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- $\delta_{D}(R, a)=\left\{q \in Q_{N} \mid q \in \delta_{N}(r, a)\right.$ for some $\left.r \in R\right\}$

But we need to consider empty string transitions

- We can just do this the same way we did with the start state

So we finally say:

- $\delta_{D}(R, a)=\left\{q \in Q_{N} \mid q \in E\left(\delta_{N}(r, a)\right)\right.$ for some $\left.r \in R\right\}$


## Building the DFA: Transition



We have built a DFA $D=\left\{Q_{D}, \Sigma, \delta_{D}, q_{0 D}, F_{D}\right\}$ that simulates NFA $N=\left\{Q_{N}, \Sigma, \delta_{N}, q_{0 N}, F_{N}\right\}$

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- $\delta_{D}(R, a)=\left\{q \in Q_{N} \mid q \in E\left(\delta_{N}(r, a)\right)\right.$ for some $\left.r \in R\right\}$

From our observations during construction, $D$ is always in a state corresponding to the subset of states $N$ could be in on the same input

We have observed that for any NFA $N$, a corresponding DFA $D$ exists that recognizes the same language as $N$

Hence, by definition of regular languages, any language recognized by an NFA is regular.

## Building the DFA: Transition



We have built a DFA $D=\left\{Q_{D}, \Sigma, \delta_{D}, q_{0 D}, F_{D}\right\}$ that simulates NFA $N=\left\{Q_{N}, \Sigma, \delta_{N}, q_{0 N}, F_{N}\right\}$

- $Q_{D}=\mathrm{P}\left(Q_{N}\right)$, the power set of $Q_{N}$
- $q_{0 D}=E\left(\left\{q_{0 N}\right\}\right)$

No, this isn't a formal proof. I'm not going to draw the little square.
But it's good enough for the book, let alone this class, and doing a formal proof would take weeks.
be in on the same input
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Hence, by definition of regular languages, any language recognized by an NFA is regular.

Next Time:
Non-Regular Languages

