Lecture 5

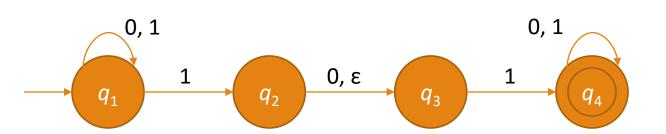
COT4210 DISCRETE STRUCTURES

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6/2/2016

PORTIONS FROM SIPSER, *INTRODUCTION TO THE THEORY OF* COMPUTATION, 3RD ED., 2013

Revisited: NFA-to-DFA Conversion

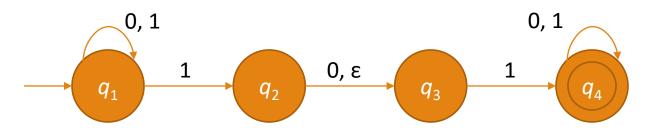


NFAs have three capabilities that DFAs don't:

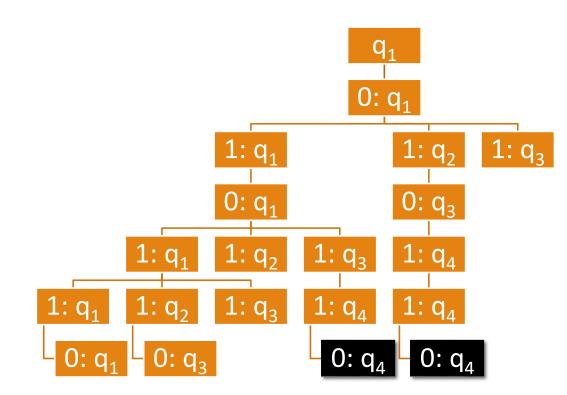
- Multiple transitions on the same symbol
- Empty-string transitions
- No transitions on some symbols

Revisited: NFA-to-DFA Conversion: Multiple Transitions

Recall our original NFA



Revisited: NFA-to-DFA Conversion: Multiple Transitions

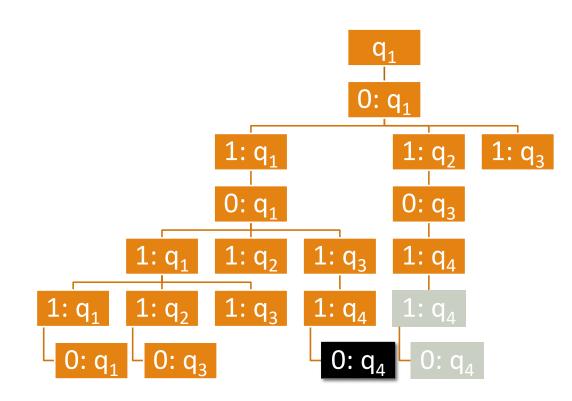


Recall our original NFA

Now recall what computation on it looks like

 Every time we have more than one choice, we spin off as many copies of the NFA as necessary to account for that choice

Revisited: NFA-to-DFA Conversion: Multiple Transitions



Recall our original NFA

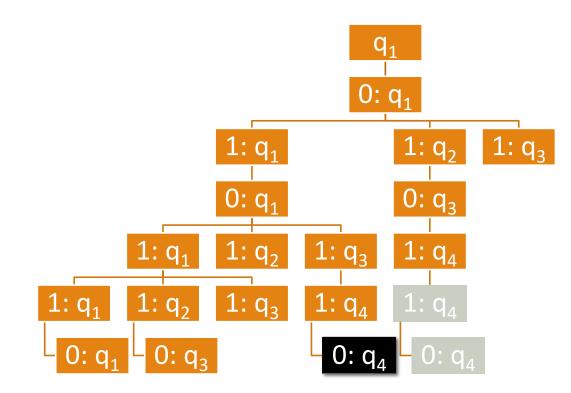
Now recall what computation on it looks like

 Every time we have more than one choice, we spin off as many copies of the NFA as necessary to account for that choice

Observe that we only *need* the copies that are actually unique against time and current states

- We only care whether we accept or not, not how many times we accept
- At a given time, it only matters whether we are in a given state or not – not how many times we are in it
- This means prior computation doesn't matter

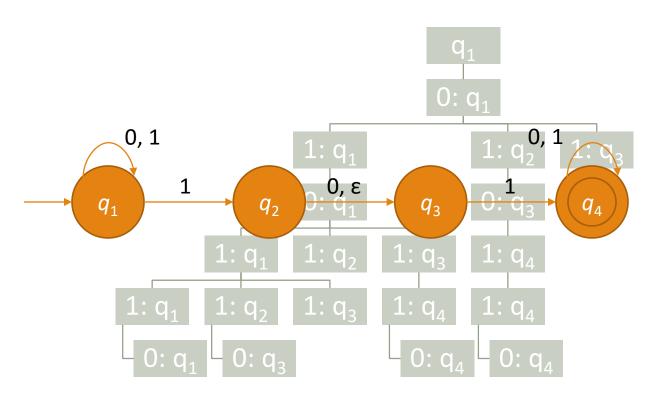
So at a given time, an NFA is in a set of states



Multiple transitions imply that at any given time, an NFA is in a *set of states*

What about empty transitions?

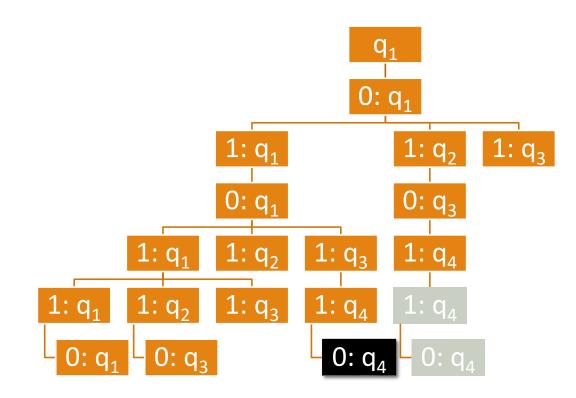
Note that the empty string never appears here



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What about empty transitions?

- Note that the empty string never appears here
- ...but everywhere q_2 does, q_3 does too

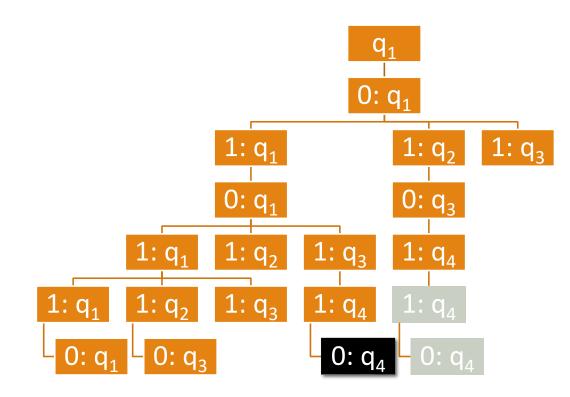


Multiple transitions imply that at any given time, an NFA is in a *set of states*

What about empty transitions?

- Note that the empty string never appears here
- ...but everywhere q_2 does, q_3 does too
- We can handle empty-string transitions by just "looking forward" at them and including them in the set of possible states at a given moment

Empty transitions are handled in computation by *including their possibilities* in the set of states



Multiple transitions imply that at any given time, an NFA is in a *set of states*

Empty transitions are handled in computation by *including their possibilities* in the set of states

What about missing transitions?

- We're already in a set of states
- If a state in that set is missing a transition from our next input symbol, it just doesn't add anything to the next set of states

Missing transitions simply *don't add anything* to the next set of states

Keep in mind our three observations about the computation process of an NFA:

- **1.** Multiple transitions imply that at any given time, an NFA is in a set of states
- 2. Empty transitions are handled in computation by *including their possibilities* in the set of states
- **3.** Missing transitions simply *don't add anything* to the next set of states

Now take this a bit further:

- The power set P(Q) of an NFA's states is the set of all possible subsets of its states
- So at any given time, the set of states an NFA is in is an element in P(Q)
- P(Q) is *itself* a set

So on a given transition, an NFA is simply transitioning from one element of P(Q) to another

Keep in mind our three observations about the computation process of an NFA:

- **1.** Multiple transitions imply that at any given time, an NFA is in a set of states
- 2. Empty transitions are handled in computation by *including their possibilities* in the set of states
- **3.** Missing transitions simply *don't add anything* to the next set of states

We have also observed that:

4. On a given transition, an NFA is simply transitioning from one element of P(Q) to another

Now consider empty and missing transitions:

- The possibilities of empty transitions are included in the set of states by look-ahead
- Missing transitions are handled by simply not adding anything to the set of states
- So given the next input symbol, we account for them completely in the next set of states

This means that **an NFA transitions from one element of P(Q) to another element of P(Q) based only on the next input symbol**

Keep in mind our three observations about the computation process of an NFA:

- **1.** Multiple transitions imply that at any given time, an NFA is in a set of states
- 2. Empty transitions are handled in computation by *including their possibilities* in the set of states
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We have also observed that:

- 4. On a given transition, an NFA is simply transitioning from one element of P(Q) to another
- 5. An NFA transitions from one element of P(Q) to another element of P(Q) based only on the next input symbol
- So while an NFA is computing, we have:
- A finite set of states it can be in, and
- A way to know which state it will be in next, given only its current state and the input symbol

Keep in mind our three observations about the computation process of an NFA:

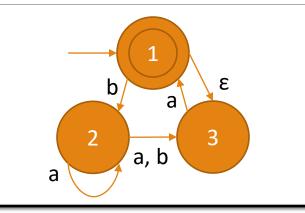
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Building the DFA

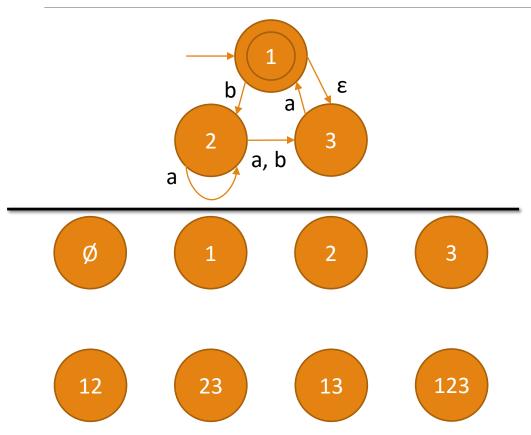


We want to build a DFA $D = \{ Q_D, \Sigma, \delta_D, q_{0D}, F_D \}$ that simulates NFA $N = \{ Q_N, \Sigma, \delta_N, q_{0N}, F_N \}$

We need to figure out:

- The state set
- The transition function
- The start state
- The final states

Building the DFA: States

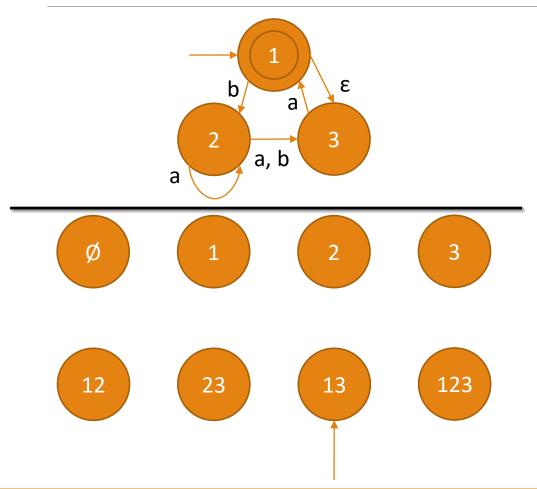


We want to build a DFA $D = \{Q_D, \Sigma, \delta_D, q_{0D}, F_D\}$ that simulates NFA $N = \{Q_N, \Sigma, \delta_N, q_{0N}, F_N\}$

The state set is the easiest part: just remember that we need to simulate being in some subset of the states of *N*, and say:

• $Q_D = P(Q_N)$, the power set of Q_N

Building the DFA: Starting



We want to build a DFA $D = \{ Q_D, \Sigma, \delta_D, q_{0D}, F_D \}$ that simulates NFA $N = \{ Q_N, \Sigma, \delta_N, q_{0N}, F_N \}$

• $Q_D = P(Q_N)$, the power set of Q_N

Next let's look at the start state

- Easy answer: the state corresponding to being in, and only in, the start state of the NFA
- ...with one wrinkle: empty-string transitions

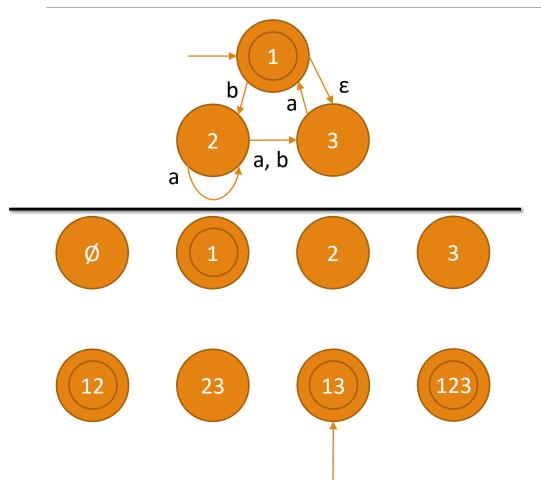
So we need the set-state containing:

• **q**_{ON}

 The states you can reach from q_{0N} with only empty-string transitions

Let's call that set-state $E({q_{0N}})$, and say: • $q_{0D} = E({q_{0N}})$

Building the DFA: Acceptance



We want to build a DFA $D = \{ Q_D, \Sigma, \delta_D, q_{0D}, F_D \}$ that simulates NFA $N = \{ Q_N, \Sigma, \delta_N, q_{0N}, F_N \}$

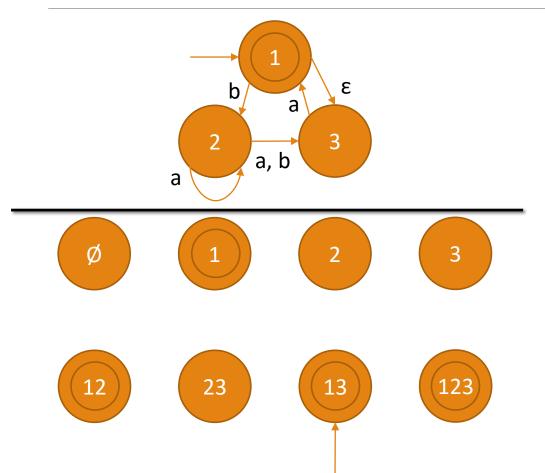
- $Q_D = P(Q_N)$, the power set of Q_N
- $\circ \boldsymbol{q}_{0D} = \mathsf{E}(\{\boldsymbol{q}_{0N}\})$

Next the accept states – which actually *are* easy

- Recall that the NFA accepts if it has any computation path to an accept state
- This means that in our computation, if there is any state we could be in that is an NFA accept state, we accept

So a state-set accepts if it *contains any accept state* from the NFA

- $F_D = \{R \in Q_D \mid R \text{ and } F_N \text{ have a common member}\}$, or
- $F_D = \{R \in Q_D \mid R \cap F_N \neq \emptyset\}$



We want to build a DFA $D = \{ Q_D, \Sigma, \delta_D, q_{0D}, F_D \}$ that simulates NFA $N = \{ Q_N, \Sigma, \delta_N, q_{0N}, F_N \}$

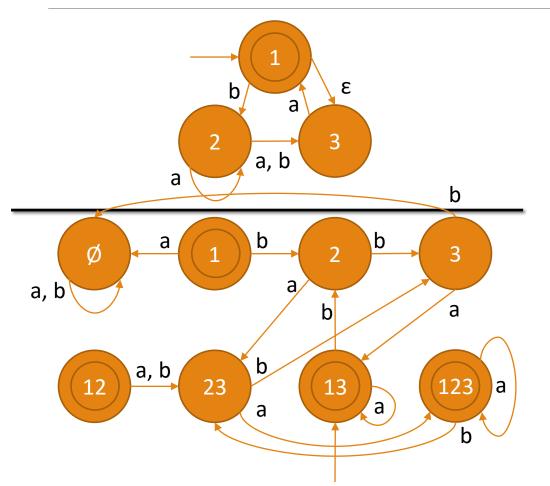
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- $\circ F_D = \{ R \in Q_D \mid R \cap F_N \neq \emptyset \}$

Now the transition function. Remember:

- The NFA transitions between *sets of states*
- We simulate that by having a state for each possible set

So to transition on a given symbol *a*, we:

- Look at *all* the NFA states we are currently simulating
- Look at all the states they can possibly transition to on a
- Transition to the set of all of those states



We want to build a DFA $D = \{ Q_D, \Sigma, \delta_D, q_{0D}, F_D \}$ that simulates NFA $N = \{ Q_N, \Sigma, \delta_N, q_{0N}, F_N \}$

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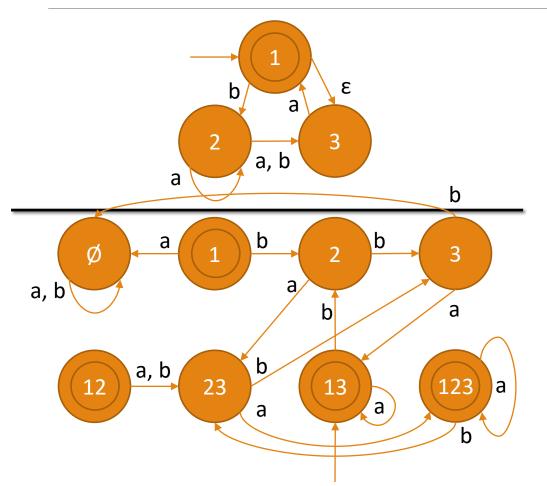
To transition on a given symbol *a*, we:

- Look at *all* the NFA states we are currently simulating
- Look at all the states *they* can possibly transition to on *a*
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So we define δ_D : $Q_D \times \Sigma \to Q_D$ as:

• $\delta_D(R, a) = \{q \in Q_N \mid q \in \delta_N(r, a) \text{ for some } r \in R\}$

• ...almost



We want to build a DFA $D = \{Q_D, \Sigma, \delta_D, q_{0D}, F_D\}$ that simulates NFA $N = \{Q_N, \Sigma, \delta_N, q_{0N}, F_N\}$

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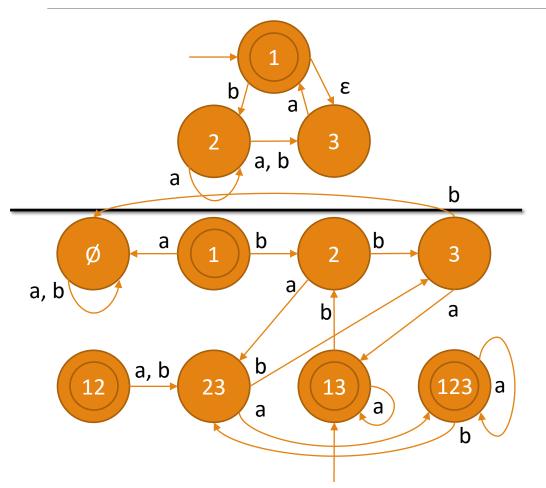
We just defined $\delta_D: Q_D \times \Sigma \to Q_D$ as: • $\delta_D(R, a) = \{q \in Q_N \mid q \in \delta_N(r, a) \text{ for some } r \in R\}$

But we need to consider empty string transitions

 We can just do this the same way we did with the start state

So we finally say:

• $\delta_D(R, a) = \{q \in Q_N \mid q \in E(\delta_N(r, a)) \text{ for some } r \in R\}$



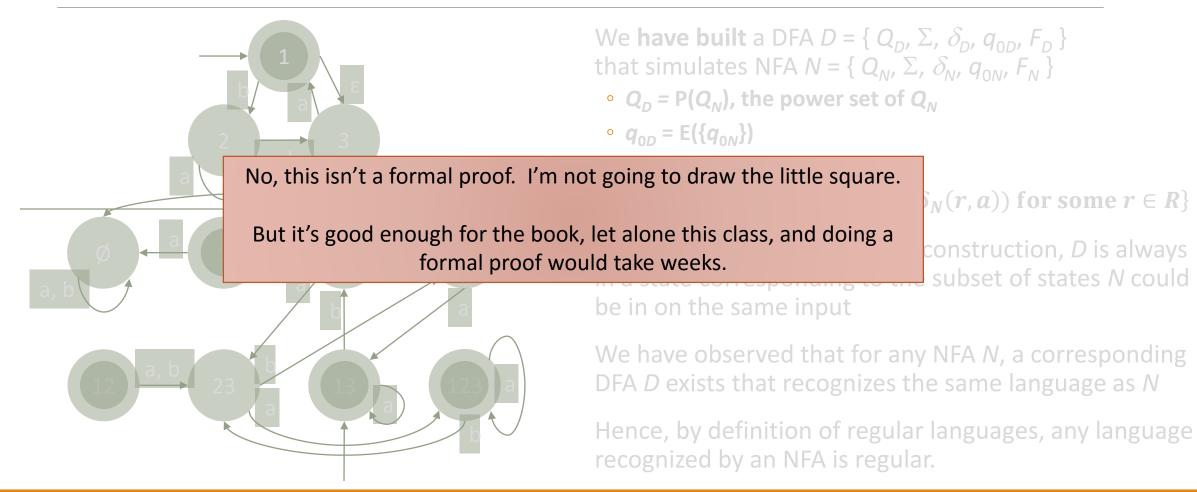
We have built a DFA $D = \{ Q_D, \Sigma, \delta_D, q_{0D}, F_D \}$ that simulates NFA $N = \{ Q_N, \Sigma, \delta_N, q_{0N}, F_N \}$

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- $\delta_D(R, a) = \{q \in Q_N \mid q \in E(\delta_N(r, a)) \text{ for some } r \in R\}$

From our observations during construction, *D* is always in a state corresponding to the subset of states *N* could be in on the same input

We have observed that for any NFA *N*, a corresponding DFA *D* exists that recognizes the same language as *N*

Hence, by definition of regular languages, any language recognized by an NFA is regular.



Next Time: Non-Regular Languages