



# CAP 5415 Computer Vision Fall 2005

Dr. Alper Yilmaz

Univ. of Central Florida

[www.cs.ucf.edu/courses/cap5415/fall2005](http://www.cs.ucf.edu/courses/cap5415/fall2005)

Office: CSB 250

Alper Yilmaz, Fall 2005 UCF



## Recap Steps in Seed Segmentation

1. Compute and smooth image histogram.
2. Detect good peaks and set thresholds
3. Apply connected component algorithm.
4. Merge small regions, split big regions

Alper Yilmaz, Fall 2005 UCF



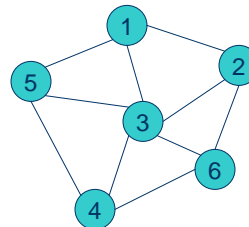
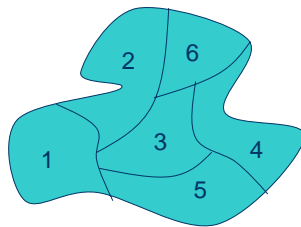
## Recap Region Growing Approaches

- Region splitting and merging
  - Region similarity function
- Phagocyte algorithm (boundary melting)
  - Compute intensity similarity between all the pixels of regions
- Likelihood ratio test
  - Two hypothesis:  $\exists$  one region,  $\exists$  two regions

Alper Yilmaz, Fall 2005 UCF



## Recap Region Adjacency Graph



Alper Yilmaz, Fall 2005 UCF



# Geometric Properties of Regions



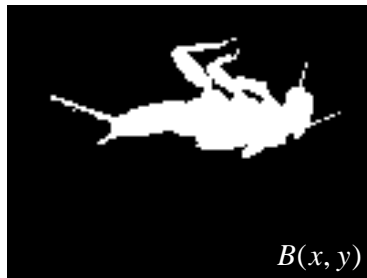
Alper Yilmaz, Fall 2005 UCF



## Region Properties



- Area
- Centroid
- Moments
- Perimeter
- Compactness
- Orientation



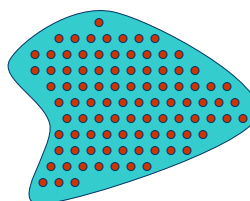
Alper Yilmaz, Fall 2005 UCF



## Area

- Number of pixels inside a region

$$A = \sum_{x=0}^m \sum_{y=0}^n B(x, y)$$



Alper Yilmaz, Fall 2005 UCF

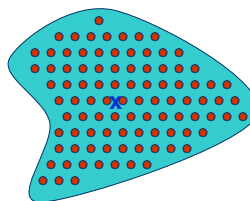


## Centroid

- Center of mass

$$\bar{x} = \frac{\sum_{x=0}^m \sum_{y=0}^n xB(x, y)}{A}$$

$$\bar{y} = \frac{\sum_{x=0}^m \sum_{y=0}^n yB(x, y)}{A}$$



Alper Yilmaz, Fall 2005 UCF



## Moments

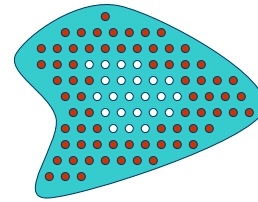
- Continuous

$$m_{pq}^i = \int \int x^p y^q B(x, y) dx dy \quad i^{\text{th}} \text{ moment}$$

- Discrete

$$m_{10}^1 = \sum_{x=0}^m \sum_{y=0}^n x B(x, y), \quad m_{01}^1 = \sum_{x=0}^m \sum_{y=0}^n y B(x, y)$$

$$m_{20}^2 = \sum_{x=0}^m \sum_{y=0}^n x^2 B(x, y), \quad m_{02}^2 = \sum_{x=0}^m \sum_{y=0}^n y^2 B(x, y), \quad m_{11}^2 = \sum_{x=0}^m \sum_{y=0}^n xy B(x, y)$$



Alper Yilmaz, Fall 2005 UCF



## Uniqueness Theorem

- The double moment sequence  $\{m_{pq}\}$  is uniquely determined by  $B(x, y)$  and conversely  $B(x, y)$  is uniquely determined by  $\{m_{pq}\}$

Alper Yilmaz, Fall 2005 UCF



## “Central” Moments

- Translation invariant
  - If same region appears in different places in the image its central moments are same

$$\mu_{pq} = \iint (x - \bar{x})^p (y - \bar{y})^q B(x, y) d(x - \bar{x})d(y - \bar{y})$$

Region centroid

Central phrase comes from centroid

Alper Yilmaz, Fall 2005 UCF



## Central Moments

$$\mu_{pq} = \iint (x - \bar{x})^p (y - \bar{y})^q B(x, y) d(x - \bar{x})d(y - \bar{y})$$

$$m_{pq}^i = \iint x^p y^q B(x, y) dx dy$$

$$\mu_{00} = m_{00} \equiv \mu$$

$$\mu_{01} = 0$$

$$\mu_{10} = 0$$

$$\mu_{20} = m_{20} - \mu \bar{x}^2$$

$$\mu_{11} = m_{11} - \mu \bar{x} \bar{y}$$

$$\mu_{02} = m_{02} - \mu \bar{y}^2$$

$$\mu_{30} = m_{30} - 3m_{20}\bar{x} + 2\mu \bar{x}^3$$

$$\mu_{21} = m_{21} - m_{20}\bar{y} - 2m_{11}\bar{x} + 2\mu \bar{x}^2 \bar{y}$$

$$\mu_{12} = m_{12} - m_{02}\bar{x} - 2m_{11}\bar{y} + 2\mu \bar{x} \bar{y}^2$$

$$\mu_{03} = m_{03} - 3m_{02}\bar{y} + 2\mu \bar{y}^3$$

Alper Yilmaz, Fall 2005 UCF



## Hu Moments

$$\mu_{pq} = \iint (x - \bar{x})^p (y - \bar{y})^q B(x, y) d(x - \bar{x}) d(y - \bar{y})$$

- Translation, rotation, scaling invariant

$$v_1 = \mu_{20} + \mu_{02}$$

$$v_2 = (\mu_{20} - \mu_{02})^2 + \mu_{11}^2$$

$$v_3 = (\mu_{30} - 3\mu_{12})^2 + (3\mu_{12} - \mu_{03})^2$$

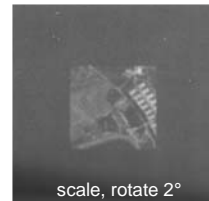
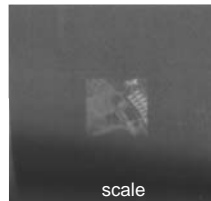
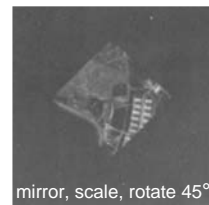
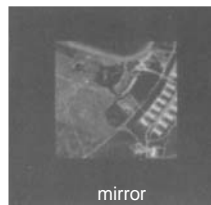
$$v_4 = (\mu_{30} + \mu_{12})^2 + (\mu_{21} + \mu_{03})^2$$

⋮

Alper Yilmaz, Fall 2005 UCF



## Example



Alper Yilmaz, Fall 2005 UCF



## Example

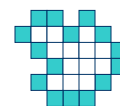
Invariant (Log)	Original	Half Size	Mirrored	Rotated 2°	Rotated 4°
$\phi_1$	6.249	6.226	6.919	6.253	6.318
$\phi_2$	17.180	16.954	19.955	17.270	16.803
$\phi_3$	22.655	23.531	26.689	22.836	19.724
$\phi_4$	22.919	24.236	26.901	23.130	20.437
$\phi_5$	45.749	48.349	53.724	46.136	40.525
$\phi_6$	31.830	32.916	37.134	32.068	29.315
$\phi_7$	45.589	48.343	53.590	46.017	40.470

Alper Yilmaz, Fall 2005 UCF



## Perimeter and Compactness

- Perimeter: Sum of pixels on the boundary of region
- Compactness
  - Circle is the most compact



$$C = \frac{\overset{\text{perimeter}}{P^2}}{\underset{\text{area}}{4\pi A}}$$

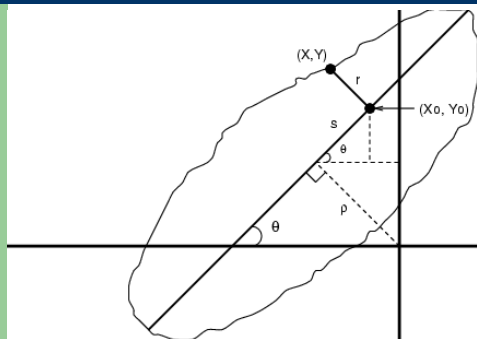


Alper Yilmaz, Fall 2005 UCF





## Region Orientation

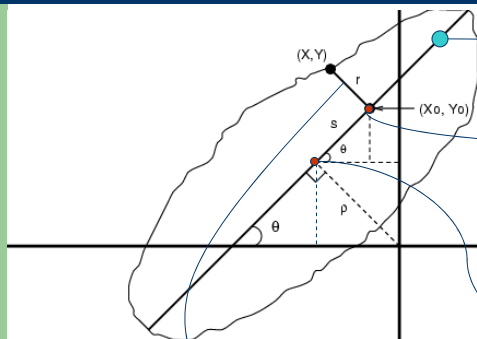


Axis of 2<sup>nd</sup> moment

Alper Yilmaz, Fall 2005 UCF



## Region Orientation



line equation  
 $x \sin \theta - y \cos \theta + \rho = 0$

$$x_0 = (-\rho \sin \theta) + s \cos \theta$$

$$y_0 = (\rho \cos \theta) + s \sin \theta$$

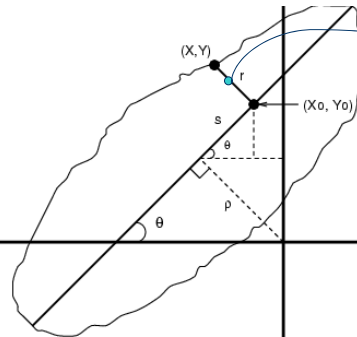
$$(-\rho \sin \theta, \rho \cos \theta)$$

Minimize  $E = \iint r^2 B(x, y) dx dy$

Alper Yilmaz, Fall 2005 UCF



## Region Orientation



$$r^2 = (x - x_0)^2 + (y - y_0)^2$$

- Substituting  $(x_0, y_0)$  in  $r^2$
- Differentiating w.r.t.  $s$
- Setting it to 0

$$s = x \cos \theta + y \sin \theta$$

- Substituting  $s$  in  $(x_0, y_0)$

$$r^2 = (x \sin \theta - y \cos \theta + \rho)^2$$

Alper Yilmaz, Fall 2005 UCF



## Region Orientation

$$r^2 = (x \sin \theta - y \cos \theta + \rho)^2$$

$$E = \iint r^2 B(x, y) dx dy$$

$$E = \iint (x \sin \theta - y \cos \theta + \rho)^2 B(x, y) dx dy$$

take derivative wrt  $\rho$  and equating it to 0  $\rightarrow$

$$A(\bar{x} \sin \theta - \bar{y} \cos \theta + \rho) = 0 \quad \text{where } (\bar{x}, \bar{y}) \text{ is centroid}$$

$$\text{Using } x' = x - \bar{x}, y' = y - \bar{y} \text{ we have } E = a \sin^2 \theta - b \sin \theta \cos \theta + c \cos^2 \theta$$

$$\text{or } E = \frac{1}{2}(a + c) - \frac{1}{2}(a - c) \cos 2\theta - \frac{1}{2}b \sin 2\theta$$

$$\text{where } a = \iint x'^2 B(x, y) dx' dy', b = \iint x' y' B(x, y) dx' dy', c = \iint y'^2 B(x, y) dx' dy'$$

Alper Yilmaz, Fall 2005 UCF

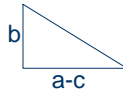


## Region Orientation

$$E = \frac{1}{2}(a+c) - \frac{1}{2}(a-c)\cos 2\theta - \frac{1}{2}b\sin 2\theta$$

take derivative wrt  $\theta$  and equating it to 0  $\rightarrow$

$$\tan 2\theta = \frac{b}{a-c}$$



$$\sin 2\theta = \pm \frac{b}{\sqrt{b^2 + (a-c)^2}}$$

$$\cos 2\theta = \pm \frac{a-c}{\sqrt{b^2 + (a-c)^2}}$$

Alper Yilmaz, Fall 2005 UCF



## Example

$$\begin{bmatrix} 0 & 0 & 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 \end{bmatrix}$$

Find: area, centroid, moments, compactness, perimeter, orientation

Alper Yilmaz, Fall 2005 UCF



## MidTerm

- October 5

Alper Yilmaz, Fall 2005 UCF