

Technical Report:

Robust Object Pose Estimation via Statistical Manifold Modeling

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Proposition 1. Given Equation 2, the distance between two object poses O_i^j and O_m^n can be computed as,

$$D(O_i^j, O_m^n) = E_X(D_{KL}(P_i^j(A|X)||P_m^n(A|X))) + D_{KL}(P_i^j(X)||P_m^n(X))$$

Proof:

Suppose that we have two PDFs, $P(A, X)$ and $Q(A, X)$,

$$\begin{aligned} D_{KL}(P(A, X)||Q(A, X)) &\equiv \iint P(A, X) \log \frac{P(A, X)}{Q(A, X)} dXdA \\ &= \iint P(A|X)P(X) \log \frac{P(A|X)P(X)}{Q(A|X)Q(X)} dXdA \\ &= \iint P(A|X)P(X) \log \frac{P(A|X)}{Q(A|X)} dXdA + \iint P(A|X)P(X) \log \frac{P(X)}{Q(X)} dXdA \\ &= \int P(X) \left\{ \int P(A|X) \log \frac{P(A|X)}{Q(A|X)} dA \right\} dX + \int \left\{ \int P(A|X) dA \right\} P(X) \log \frac{P(X)}{Q(X)} dX \\ &= E_X \left\{ \int P(A|X) \log \frac{P(A|X)}{Q(A|X)} dA \right\} + \int P(X) \log \frac{P(X)}{Q(X)} dX \\ &= E_X\{D_{KL}(P(A|X)||Q(A|X))\} + D_{KL}(P(X)||Q(X)) \end{aligned}$$

Combining the above derivation and Equation (2), i.e.,

$$D(O_i^j, O_m^n) = D_{KL}(P_i^j(A, X)||P_m^n(A, X)), \text{ then we have,}$$

$$D(P_i^j(O), P_m^n(O)) = E_X(D_{KL}(P_i^j(A|X)||P_m^n(A|X))) + D_{KL}(P_i^j(X)||P_m^n(X))$$

Proposition 2. If A_1, \dots, A_K are independent given \mathbf{X} , and a one-to-one part correspondence $f_{map}(Q_k^{i,j}) = Q_k^{m,n}$ exists, then the following equation holds,

$$E_X\{D_{KL}(P_i^j(A|\mathbf{X})||P_m^n(A|\mathbf{X}))\} = E_X\left(\sum_{k=1}^K D_{KL}(P_i^j(A_k|\mathbf{X})||P_m^n(A_k|\mathbf{X}))\right)$$

where $P_i^j(A_k|\mathbf{X})$ is the conditional PDF of part A_k given \mathbf{X} .

Proof:

In the proof of Proposition 1, if we further assume that A and X are independent, then we have $D_{KL}(P(A, X)||Q(A, X)) = E_X\{D_{KL}(P(A|X)||Q(A|X))\} + D_{KL}(P(X)||Q(X)) = D_{KL}(P(A)||Q(A)) + D_{KL}(P(X)||Q(X))$.

Based on this observation, for two PDFs $P(X)$ and $Q(X)$ and $X = (X_1, X_2, \dots, X_n)$, where X_i and X_j are independent, we can obtain $D_{KL}(P(X)||Q(X)) = \sum_{i=1}^n D_{KL}(P(X_i)||Q(X_i))$.

Since A_1, \dots, A_K are independent given \mathbf{X} , then,

$$E_X\{D_{KL}(P_i^j(\mathbf{A}|\mathbf{X})||P_m^n(\mathbf{A}|\mathbf{X}))\} = E_X\left(\sum_{k=1}^K D_{KL}(P_i^j(A_k|\mathbf{X})||P_m^n(A_k|\mathbf{X}))\right)$$