NON-CHRONOLOGICAL VIDEO SYNOPSIS AND INDEXING

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Problem Introduction

 Millions of surveillance cameras around the world
 Constantly recording video
 Time consuming to review each one











Objective

□ Generate a video summary

Input: Long video



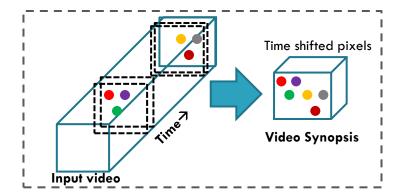
Source: www.cs.huji.ac.il/~yaelpri/

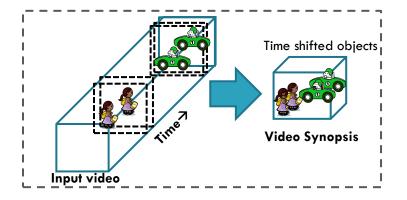
Output: Short video

Approaches Overview

Low-level video summary

Object-based video summary





Low-level video summary

PIXEL-BASED

Synopsis by energy minimization

Goal: Find a mapping (M) for each pixel that minimizes:

$$E(M) = E_a(M) + \alpha E_d(M)$$
Activity cost Discontinuity cost

□ The mapping *M* represents time shifts

Number of foreground pixels not in summary video

□ Foreground pixel:

$$\chi(x, y, t) = \|I(x, y, t) - B(x, y, t)\|$$

Respective pixel in background image

Pixel in the input image



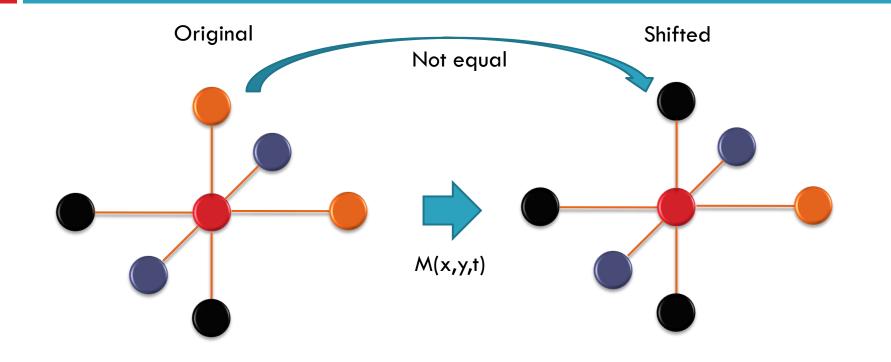
Discontinuity Cost

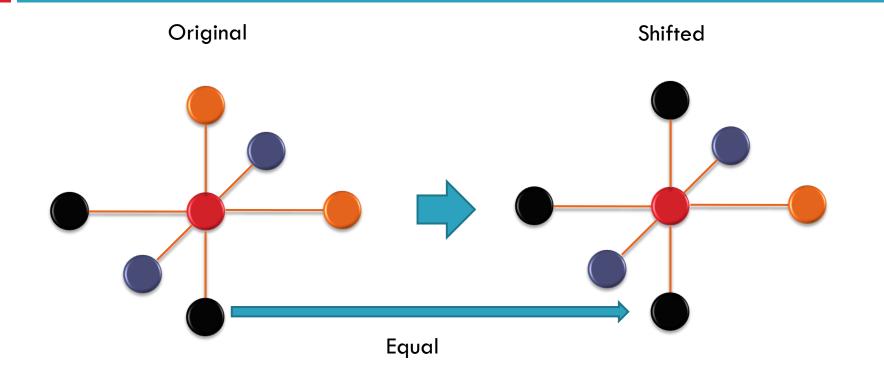
Does a pixel shift preserve its neighborhood ? Look at a spatio-temporal neighborhood: 4 spatial neighbors 2 temporal neighbors

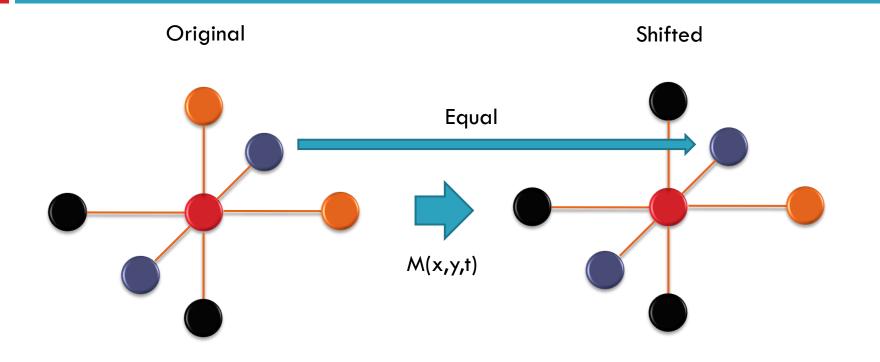
Discontinuity Cost

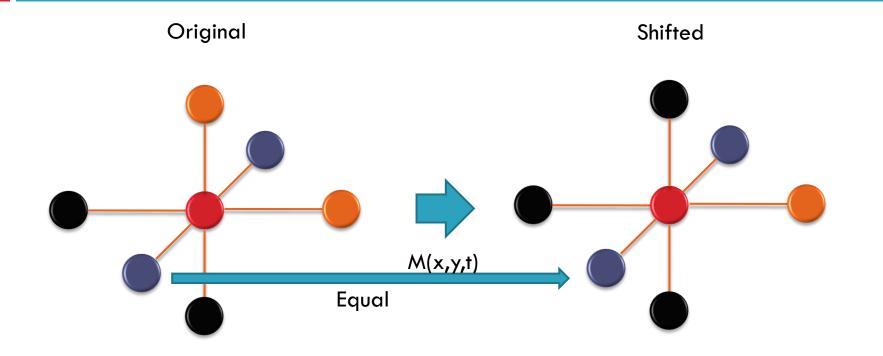
Original

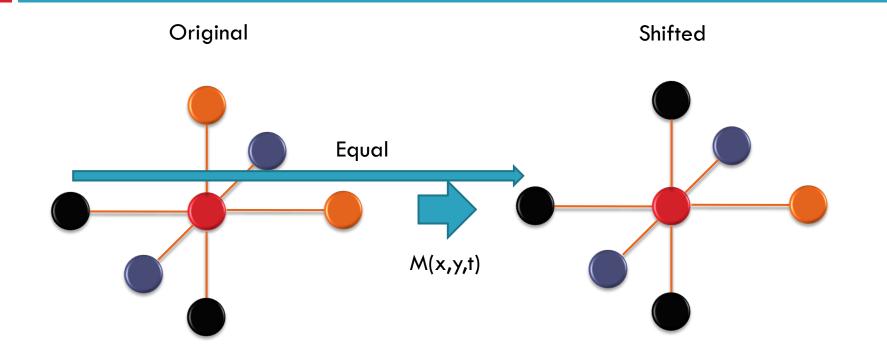
A pixel in the input video

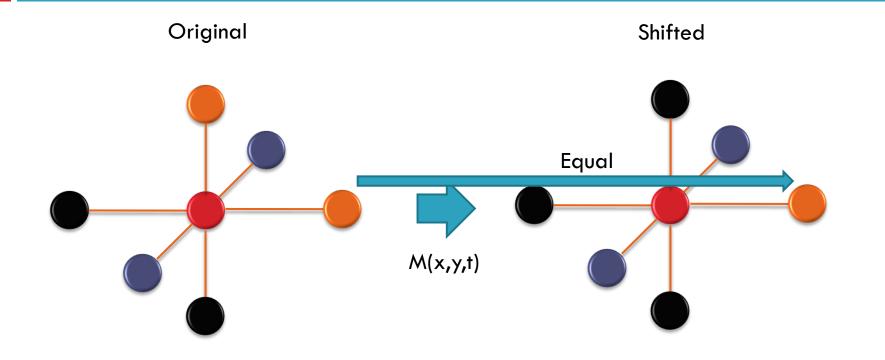












Drawbacks of Pixel-based Summary

Limited to satisfying local properties:

Such as visible seams.

- High computational cost
- □ Solution:

Incorporate high-level analysis

Object-based Video Synopsis

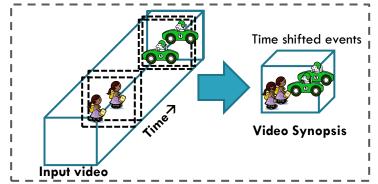
Object-based Video Synopsis

Objective:

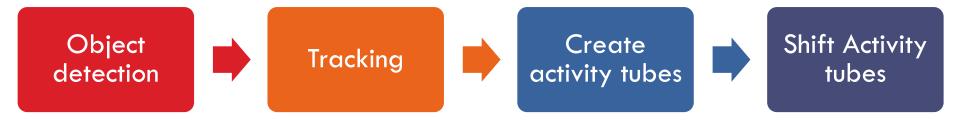
- Create synopsis of a video
 - Combine activities from
 - different times

Approach:

- Object detection and tracking.
- Generate action tubes.



Main Algorithmic Steps



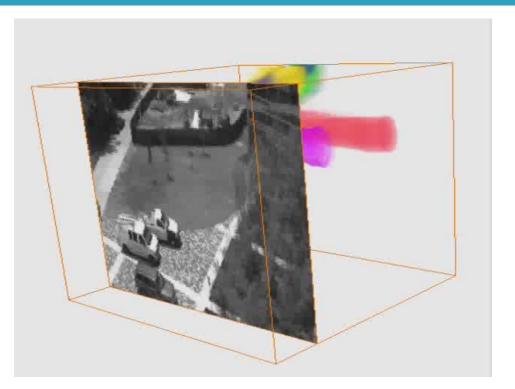
Object Detection

•Background model: •Temporal median over 4 minutes of data



Create Activity Tubes

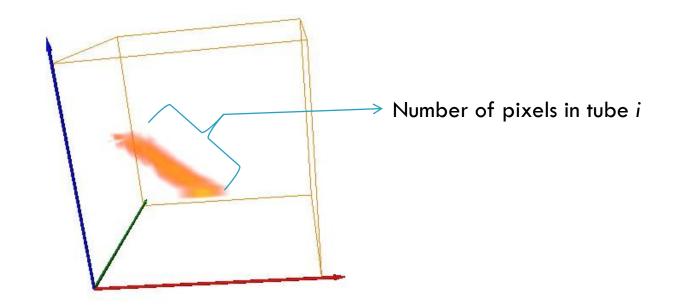
- Trace tracked objects:
 - Segment tubes
 - Label tubes



Shift Tubes

Energy function:

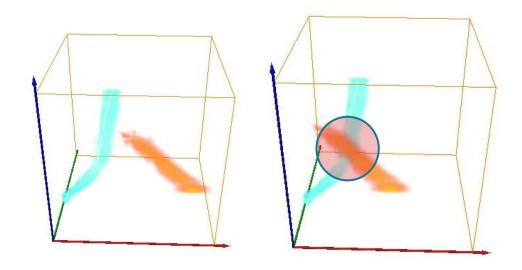
E =<u>activity cost</u> + overlap cost + temporal consistency cost



Shift Tubes

□ Energy function:

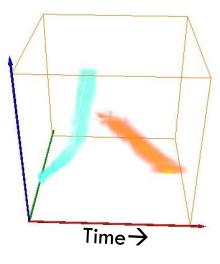
E = activity cost + <u>overlap cost</u> + temporal consistency cost

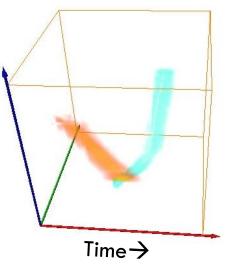


Shift Tubes

□ Energy function:

E = activity cost + overlap cost + temporal consistency cost





Blue then orange tube

Orange then blue

Video Summarization Results

Results



Results

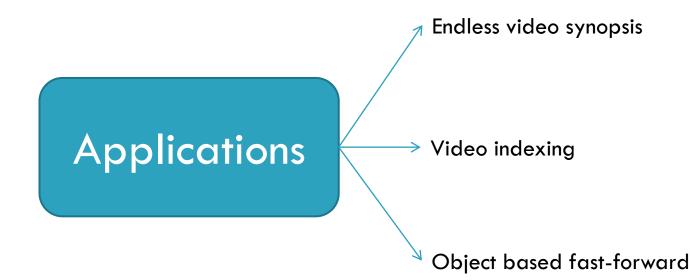


Results



Other Applications

□ Using the same principles:



Can we do better?

- □ Can we avoid background subtraction?
- □ Can we avoid tracking?
- Improve computational efficiency
- New application domains:
 - UAV Videos, P-T-Z Surveillance Cameras etc

Thank you

