

Lecture-11

Rate of Convergence of CG

Algorithm 5.2

Given x_0 ;

set $r_0 \leftarrow Ax_0 - b$, $p_0 \leftarrow -r_0$, $k \leftarrow 0$

While $r_k \neq 0$

$$\mathbf{a}_k \leftarrow -\frac{r_k^T r_k}{p_k^T A p_k};$$

$$x_{k+1} \leftarrow x_k + \mathbf{a}_k p_k;$$

$$r_{k+1} \leftarrow r_k + \mathbf{a}_k A p_k;$$

$$\mathbf{b}_{k+1} \leftarrow \frac{r_{k+1}^T r_{k+1}}{r_k^T r_k};$$

$$p_{k+1} \leftarrow -r_{k+1} + \mathbf{b}_{k+1} p_k;$$

$$k \leftarrow k + 1;$$

end (while)

We only need to know values of x , p and r only for 2 iterations.

Major computations: matrix- vector product, two inner products, and three vector sums.

Key points

- According to theorem 5.3 Algorithm 5.2 should converge at most n steps.
- Convergence less than n iterations, depending on the eigenvalues of matrix A .
- If A dose not have favorable eigenvalues, then precondition A to get faster convergence.

Theorem 5.4

If A has only r distinct eigenvalues, then the CG iteration will terminate at the solution in at most r iterations.

Main points

Want to show:

$$\|x_{k+1} - x^*\|_A^2 \leq \min_{P_k} \max_{1 \leq i \leq n} [1 + I_i P_k(I_i)]^2 \|x_0 - x^*\|_A^2$$

Use this: (Theorem 5.3)

Define polynomial $P_k^*(A) = g_0 I + g_1 A + \dots + g_k A^k$

Use orthogonal eigenvectors n_i of A .

Show n_i are also eigenvectors of $P_k(A)$

Rate of Convergence

$$x_{k+1} = x_0 + a_0 p_0 + \dots + a_k p_k \quad \text{By construction}$$

$$x_{k+1} = x_0 + g_0 r_0 + g_1 A r_0 + \dots + g_k A^k r_0$$

Define polynomial: (Theorem 5.3)

$$P_k^*(A) = g_0 I + g_1 A + \dots + g_k A^k$$

Therefore $x_{k+1} = x_0 + P_k^*(A)r_0 \quad (\text{D})$

Now

$$\frac{1}{2} \|x - x^*\|_A^2 = f(x) - f(x^*) \quad \|z\|_A^2 = z^T A z$$

$$f(x) = \frac{1}{2} x^T A x - b^T x$$

Rate of Convergence

$$\begin{aligned}
\frac{1}{2} \|x - x^*\|_A^2 &= \frac{1}{2} (x - x^*)^T A (x - x^*) \\
&= \frac{1}{2} (x^T - x^{*T}) (Ax - Ax^*) \\
&= \frac{1}{2} x^T Ax - \frac{1}{2} x^{*T} Ax - \frac{1}{2} x^T Ax^* + \frac{1}{2} x^{*T} Ax^* \\
&= \frac{1}{2} x^T Ax - \frac{1}{2} b^T x - \frac{1}{2} x^T b + \frac{1}{2} x^{*T} Ax^* \\
&= \frac{1}{2} x^T Ax - \frac{1}{2} b^T x - \frac{1}{2} x^T b + x^{*T} Ax^* - \frac{1}{2} x^{*T} Ax^* \\
&= \frac{1}{2} x^T Ax - \frac{1}{2} b^T x - \frac{1}{2} x^T b + x^{*T} b - \frac{1}{2} x^{*T} Ax^* \\
&= \frac{1}{2} x^T Ax - b^T x - \left(\frac{1}{2} x^{*T} Ax^* - b^T x^* \right) \\
&= f(x) - f(x^*)
\end{aligned}$$

$$f(x) = \frac{1}{2} x^T Ax - b^T x$$

$$\begin{aligned}
\frac{1}{2} \|x - x^*\|_A^2 &= \frac{1}{2} (x - x^*)^T A (x - x^*) = f(x) - f(x^*) \\
x_{k+1} &= x_0 + \mathbf{a}_0 p_0 + \dots + \mathbf{a}_k p_k && \text{By construction} \\
&&& f(x) = \frac{1}{2} x^T Ax - b^T x
\end{aligned}$$

According to Theorem 5.2 x_{k+1} minimizes f , hence $\|x - x^*\|_A^2$

Or

$$\|x_0 + P_k^*(A)r_0 - x^*\|_A^2 \quad x_{k+1} = x_0 + P_k^*(A)r_0 \quad \text{From (D)}$$

Therefore, P_k^* solves the following problem:

$$\min_{P_k} \|x_0 + P_k(A)r_0 - x^*\|_A^2$$

We know $r_0 = Ax_0 - b = Ax_0 - Ax^* = A(x_0 - x^*)$

$$\begin{aligned}
 x_{k+1} - x^* &= x_0 + P_k^*(A)r_0 - x^* & x_{k+1} &= x_0 + P_k^*(A)r_0 \\
 &= (x_0 - x^*) + P_k^*(A)r_0 & \text{From (D)} \\
 &= (x_0 - x^*) + P_k^*(A)A(x_0 - x^*) \\
 &= [I + P_k^*(A)A](x_0 - x^*) \quad (\text{A})
 \end{aligned}$$

Assume $\mathbf{n}_i, \mathbf{l}_i$ are eigenvectors & eigenvalues of A

$$x_0 - x^* = \sum_{i=1}^n \mathbf{x}_i v_i$$

Show \mathbf{n}_i are also eigenvectors of

$$P_k^*(A) = \mathbf{g}_0 I + \mathbf{g}_1 A + \dots + \mathbf{g}_k A^k$$

$$\begin{aligned}
 P_k(A)\mathbf{n}_i &= \mathbf{g}_0 I \mathbf{n}_i + \mathbf{g}_1 A \mathbf{n}_i + \mathbf{g}_2 A^2 \mathbf{n}_i + \dots + \mathbf{g}_k A^k \mathbf{n}_i \\
 P_k(A)\mathbf{n}_i &= \mathbf{g}_0 \mathbf{n}_i + \mathbf{g}_1 \mathbf{l}_i \mathbf{n}_i + \mathbf{g}_2 \mathbf{l}_i A \mathbf{n}_i + \dots + \mathbf{g}_k A^{k-1} \mathbf{l}_i \mathbf{n}_i \\
 P_k(A)\mathbf{n}_i &= \mathbf{g}_0 \mathbf{n}_i + \mathbf{g}_1 \mathbf{l}_i \mathbf{n}_i + \mathbf{g}_2 \mathbf{l}_i^2 \mathbf{n}_i + \dots + \mathbf{g}_k A^{k-2} \mathbf{l}_i^2 \mathbf{n}_i \\
 P_k(A)\mathbf{n}_i &= \mathbf{g}_0 \mathbf{n}_i + \mathbf{g}_1 \mathbf{l}_i \mathbf{n}_i + \mathbf{g}_2 \mathbf{l}_i^2 \mathbf{n}_i + \dots + \mathbf{g}_k \mathbf{l}_i^k \mathbf{n}_i \\
 P_k(A)\mathbf{n}_i &= (\mathbf{g}_0 + \mathbf{g}_1 \mathbf{l}_i + \mathbf{g}_2 \mathbf{l}_i^2 + \dots + \mathbf{g}_k \mathbf{l}_i^k) \mathbf{n}_i \\
 P_k(A)\mathbf{n}_i &= P(\mathbf{l}_i) \mathbf{n}_i
 \end{aligned}$$

Therefore

$$\text{We know } x_0 - x^* = \sum_{i=1}^n \mathbf{x}_i v_i$$

$$x_{k+1} - x^* = [I + P_k^*(A)A](x_0 - x^*) \quad \text{From (A)}$$

$$x_{k+1} - x^* = \sum_{i=1}^n [I + P_k^*(A)A]\mathbf{x}_i v_i$$

$$x_{k+1} - x^* = \sum_{i \neq l} [\mathbf{x}_i v_i + P_k^*(A)A\mathbf{x}_i v_i]$$

$$x_{k+1} - x^* = \sum_{i=l} [\mathbf{x}_i v_i + P_k^*(A)\mathbf{I}_l \mathbf{x}_i v_i]$$

$$x_{k+1} - x^* = \sum_{i=l} [\mathbf{x}_i v_i + \mathbf{I}_l P_k^*(\mathbf{I}_l) \mathbf{x}_i v_i]$$

$$x_{k+1} - x^* = \sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i v_i$$

$$x_{k+1} - x^* = \sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i v_i$$

$$\|x_{k+1} - x^*\|_A^2 = \left(\sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i \mathbf{n}_i^T \right) A \left(\sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i \mathbf{n}_i \right)$$

$$\|x_{k+1} - x^*\|_A^2 = \left(\sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i \mathbf{n}_i^T \right) \left(\sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i A \mathbf{n}_i \right)$$

$$\|x_{k+1} - x^*\|_A^2 = \left(\sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i \mathbf{n}_i^T \right) \left(\sum_{i=l} [1 + \mathbf{I}_l P_k^*(\mathbf{I}_l)] \mathbf{x}_i \mathbf{l} \mathbf{n}_i \right)$$

$$\|x_{k+1} - x^*\|_A^2 = \sum_{i=l}^n \mathbf{I}_i [1 + \mathbf{I}_i P_k^*(\mathbf{I}_i)]^2 \mathbf{x}_i^2 \quad \text{Orthogonal eigenvectors}$$

$$\|x_{k+1} - x^*\|_A^2 = \sum_{i=l}^n \mathbf{I}_i [1 + \mathbf{I}_i P_k(\mathbf{I}_i)]^2 \mathbf{x}_i^2$$

Since polynomial generated by GC is optimal

$$\|x_{k+1} - x^*\|_A^2 = \min_{P_k} \sum_{i=1}^n \mathbf{I}_i [1 + \mathbf{I}_i P_k(\mathbf{I}_i)]^2 \mathbf{x}_i^2$$

$$\|x_{k+1} - x^*\|_A^2 \leq \min_{P_k} \max_{1 \leq i \leq n} [1 + \mathbf{I}_i P_k(\mathbf{I}_i)]^2 \left(\sum_{j=1}^n \mathbf{I}_j \mathbf{x}_j^2 \right)$$

$$(C) \quad \|x_{k+1} - x^*\|_A^2 \leq \min_{P_k} \max_{1 \leq i \leq n} [1 + \mathbf{I}_i P_k(\mathbf{I}_i)]^2 \|x_0 - x^*\|_A^2 \quad x_0 - x^* = \sum_{i=l}^n \mathbf{x}_i v_i$$

$$(B) \quad \min_{P_k} \max_{1 \leq i \leq n} [1 + \mathbf{I}_i P_k(\mathbf{I}_i)]^2$$

Convergence

$$\begin{aligned} x_0 - x^* &= \sum_{i=1}^n \mathbf{x}_i v_i \\ \|x_0 - x^*\|_A^2 &= \sum_{i=1}^n \mathbf{x}_i v_i^T A \sum_{i=1}^n \mathbf{x}_i v_i \\ &= \sum_{i=1}^n \mathbf{x}_i v_i^T \sum_{i=1}^n \mathbf{x}_i A v_i \\ &= \sum_{i=1}^n \mathbf{x}_i v_i^T \sum_{i=1}^n \mathbf{x}_i \mathbf{I}_i v_i \\ &= \sum_{i=1}^n \mathbf{x}_i^2 \mathbf{I}_i \end{aligned}$$