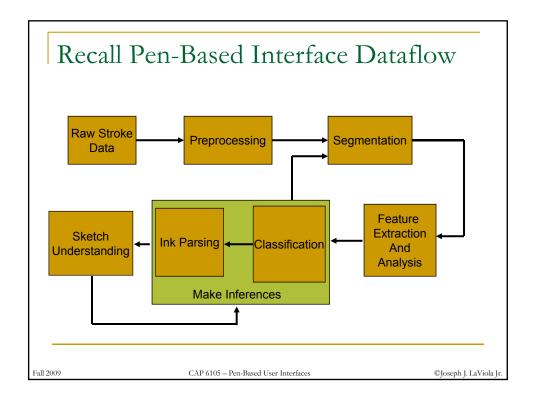
## Ink Segmentation

Lecture #7: Ink Segmentation Joseph J. LaViola Jr. Fall 2009

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## Segmentation

- Determine which strokes go together
- Determine which strokes should be apart
- Can be done in real-time or in batch
- Often uses proximity and timing information

$$y = \frac{1}{\lambda} x^{\lambda}$$

$$y = x^{\lambda} e^{-\frac{1}{\lambda}t}$$

5 K L

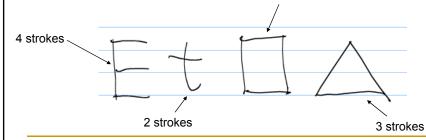
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## Grouping Strokes Together

- Why? Multiple strokes can form one symbol
  - □ math symbols, shapes, etc...
  - want to pass all strokes that make up a symbol to recognizer



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# Grouping Strokes Together – Basic Approach

- Check to see if two or more strokes intersect
  - if they do then group them together
- Can use simple line segment intersection tests
- Problems
  - □ ink strokes ink ≠ polyline
  - what if two strokes do not intersect but should be grouped together?
  - what if two strokes intersect but should not be grouped together?

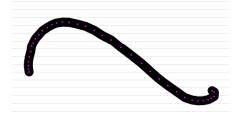
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#### Ink Strokes and Polylines

- Polylines are internal representation
- Ink has width
  - need requires more robust intersection
- One approach
  - find silhouettes
  - do intersection testing on them



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### Robust Stroke Intersection (Part 1)

```
Input: Stroke s_i, a set of candidate strokes CS = \{s_1, s_2, \dots, s_n\}.
Output: True or false
ROBUSTINTERSECTION(s_i, CS)
         P \leftarrow Points(s_i)
         cs_1 \leftarrow Circle(P_1, \frac{PenInkWidth()}{2})
(2)
         cs_2 \leftarrow Circle(P_n, \frac{PenInkWidth()}{2})
         sil_1 \leftarrow Polygon(ComputeStrokeEdges(s_i))
(5)
         for
each Stroke stk \in CS
(6)
             Q \leftarrow Points(stk)
            cstk_1 \leftarrow Circle(Q_1, \frac{PenInkWidth()}{2})
(7)
            cstk_2 \leftarrow Circle(Q_n, \frac{PenInkWidth()}{2})
(8)
(9)
             sil_2 \leftarrow Polygon(ComputeStrokeEdges(stk))
(10)
             if cs_1 \cap cstk_1 or cs_1 \cap cstk_2 or cs_1 \cap sil_2 or cs_2 \cap cstk_1 or cs_2 \cap cstk_2
             or cs_2 \cap sil_2 or sil_1 \cap cstk_1 or sil_1 \cap cstk_2 or sil_1 \cap sil_2
(11)
                 return true
(12)
         return false
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```

## Robust Stroke Intersection (Part 2)

```
Input: Stroke s_i
Output: A list of silhouette points
ComputeStrokeEdges(s_i.)
           P \leftarrow Points(s_i)
(1)
(2)
           if n < 3
(3)
                return P
(4)
(5)
           for i = 1 to n - 1
(6)
                \vec{v_1} \leftarrow Vector(Y(P_{i+1}) - Y(P_i), -(X(P_{i+1}) - X(P_i)))
                \vec{v_2} \leftarrow Vector(-(Y(P_{i+1}) - Y(P_i)), X(P_{i+1}) - X(P_i))
(7)
                Ppts1_i \leftarrow P_i + pen_w \frac{\vec{v_1}}{\|\vec{v_1}\|}
                Ppts2_i \leftarrow P_i + pen_w \frac{v_2}{\|\vec{v_2}\|}
(9)
                if i = n - 1
(10)
                   Ppts1_i \leftarrow P_{i+1} + pen_w \frac{\vec{v_1}}{\|\vec{v_1}\|}
Ppts2_i \leftarrow P_{i+1} + pen_w \frac{\vec{v_2}}{\|\vec{v_2}\|}
(11)
(12)
```

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### Robust Intersection (Part 2) -cont'd

```
for i = 1 to n - 1
if i = 1
(14)
(15)
                 Silpts1_i = Ppts1_i
(16)
                 Silpts2_i = Ppts2_i
(17)
                 continue
             if i = n - 1
(18)
(19)
                 Silpts1_{i+1} = Ppts1_{i+1}
(20)
                 Silpts2_{i+1} = Ppts2_{i+1}
(21)
                 continue
             \vec{v_3} \leftarrow Vector(X(Ppts1_{i-1}) - X(Ppts1_i), Y(Ppts1_{i-1}) - Y(Ppts1_i))
(22)
             \vec{v_4} \leftarrow Vector(X(Ppts1_i) - X(Ppts1_{i+1}), Y(Ppts1_i) - Y(Ppts1_{i+1}))
(23)
(24)
             intpt \leftarrow LineIntersection(Ppts1_i, \frac{\vec{v_3}}{\|\vec{v_3}\|}, Ppts1_{i+1}, \frac{\vec{v_4}}{\|\vec{v_4}\|})
(25)
             if \ intpt = \emptyset
                 Silpts1_i = Ppts1_i
(26)
(27)
             else
(28)
                 Silpts1_i = intpt
(29)
             \vec{v_5} \leftarrow Vector(X(Ppts2_{i-1}) - X(Ppts2_i), Y(Ppts2_{i-1}) - Y(Ppts2_i))
             \vec{v_6} \leftarrow Vector(X(Ppts2_i) - X(Ppts2_{i+1}), Y(Ppts2_i) - Y(Ppts2_{i+1}))
(30)
(31)
             intpt \leftarrow LineIntersection(Ppts2_{i}, \frac{\vec{v_{5}}}{\|\vec{v_{5}}\|}, Ppts2_{i+1} \frac{\vec{v_{6}}}{\|\vec{v_{6}}\|},)
(32)
             if \ intpt = \emptyset
(33)
                 Silpts2_i = Ppts2_i
(34)
(35)
                 Silpts2_i = intpt
(36)
         {\bf return}\ CreatePointList(Silpts1,Silpts2,Silpts1_0)
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```

## Grouping Strokes Together – Extending Basic Approach

- What if two or more strokes should be grouped together but do not intersect?
- Need other information
  - timing info
  - spatial info



- If two strokes are close together and they have been drawn consecutively then there is a good chance they should be grouped together
  - still has problems

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## Grouping Strokes Together – Using Recognition

- To help with segmentation use recognizer (Smithies et. al 1999)
- For each stroke
  - take last k strokes and send to recognizer
  - look for symbol recognitions with highest confidence level
  - group based on highest confidence level
- When all else fails
  - use domain knowledge
  - easy to use UI correction techniques

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### Inadvertent Stroke Grouping

- What if strokes are intersecting but should not be grouped together?
- Must look at context
  - would such a symbol make sense in its surroundings?
  - example perpendicular symbol over 6 does not make sense (so ungroup to make 1 and division line)
- UI correction also important (tools for breaking strokes apart)

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## Breaking Strokes Apart

- Why? Want to break symbols (groups of strokes) into logical blocks
  - Examples include mathematical expressions on a page, multiple diagrams or drawings
- Starts moving into sketch understanding and sketch parsing
- As with grouping, using recognition engine can help
- Domain knowledge also important

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### Breaking Strokes Apart – Basic Approach

- Lines of math
- Do a horizontal line sweep, if white space is found, break up strokes into expressions
  - a threshold could be used just in case of a few pixels found in sweep
- Another approach
  - Look at histogram of points
    - rotate ink 90 degrees
    - project onto x-axis
    - find minima

 $y = 3x^2 + 6$ 

y = 5 x2 - 4

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### Strategy Summary

- Can go a long way with speed data, proximity info, and intersection testing
  - does not work every time
- Use recognizer to help find segmentations that make sense
- Make use of domain knowledge
- Have easy to use UI techniques for corrections
- More on this when we get to sketch understanding

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### Readings

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- Smithies, Steve, Kevin Novins, and James Arvo. A Handwriting-Based Equation Editor. In Proceedings of Graphics Interface'99, 84-91, 1999.
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