



CAP 5415 Computer Vision Fall 2005

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www.cs.ucf.edu/courses/cap5415/fall2005

Office: CSB 250

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Histogram Segmentation Code

```
%smooth
for i=1:5
    hst=conv2(hst,gauss,'same');
end
%compute derivative
dr1=conv2(hst,dr,'same');
%find peaks and valleys
pw =dr1(1:254).*dr1(2:255);
peaks_valleys(find(pw<0))=1;

control=find(peaks_valleys==1);
for i=1:size(control,2)
    if (dr1(control(i)-2)>0)
        valleys(control(i))=1;
    end
    if (dr1(control(i)-2)<0)
        peaks(control(i))=1;
    end
end

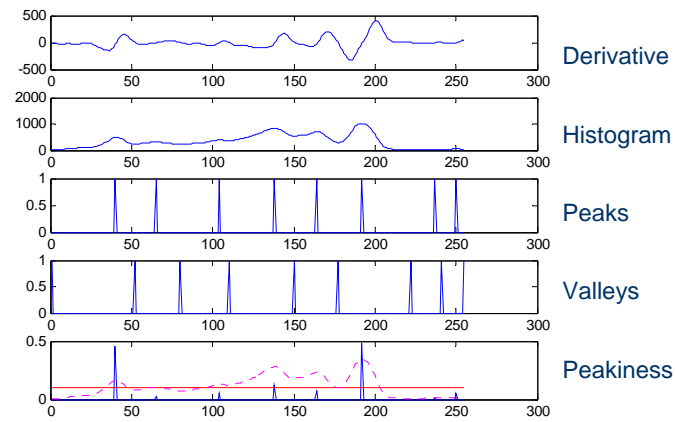
peaklocs=find(peaks==1);
valleylocs=find(valleys==1);

current_valley=1;
for i=1:size(peaklocs,2)
    Va = hst(valleylocs(current_valley));
    Vb = hst(valleylocs(current_valley+1));
    P = hst(peaklocs(i));
    W = valleylocs(current_valley+1) -
        valleylocs(current_valley);
    N = 0 ;
    for
        j=valleylocs(current_valley):valleylocs
            (current_valley+1)
            N = N + hst(j);
    end
    vall = 1 - ((Va+Vb)/(2*P));
    val2 = 1 - (N/(W*P));
    if (vall>0 && val2>0)
        peakiness(peaklocs(i)) = vall*val2;
    end;
    current_valley = current_valley +1;
end
```

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Plots



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Recap Region Properties

- Area
- Centroid
- Moments
- Perimeter
- Compactness
- Orientation

$$A = \sum_{x=0}^m \sum_{y=0}^n B(x, y)$$

$$\bar{x} = \frac{\sum_{x=0}^m \sum_{y=0}^n xB(x, y)}{A} \quad \bar{y} = \frac{\sum_{x=0}^m \sum_{y=0}^n yB(x, y)}{A}$$

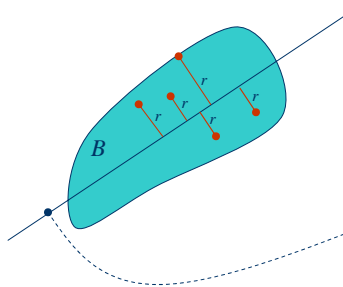
$$\mu_{pq} = \iint (x - \bar{x})^p (y - \bar{y})^q B(x, y) \, d(x - \bar{x})d(y - \bar{y})$$

$$C = \frac{\text{Perimeter}^2}{4\pi A}$$

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Recap Region Orientation



$$E = \iint r^2 B(x, y) dx dy$$

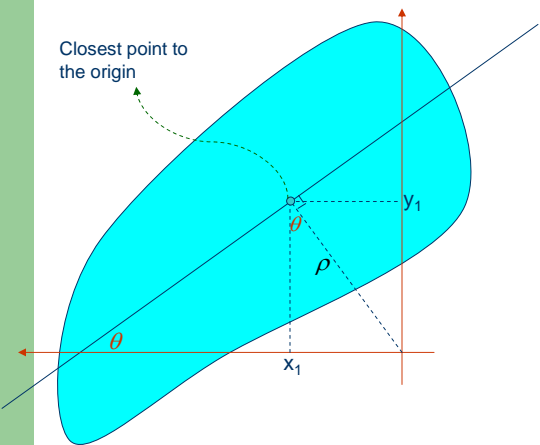
Axis of 2nd moment

$$m_{20}^2 = \sum_{x=0}^m \sum_{y=0}^n x^2 B(x, y)$$
$$m_{02}^2 = \sum_{x=0}^m \sum_{y=0}^n y^2 B(x, y)$$
$$m_{11}^2 = \sum_{x=0}^m \sum_{y=0}^n xy B(x, y)$$

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Recap Region Orientation

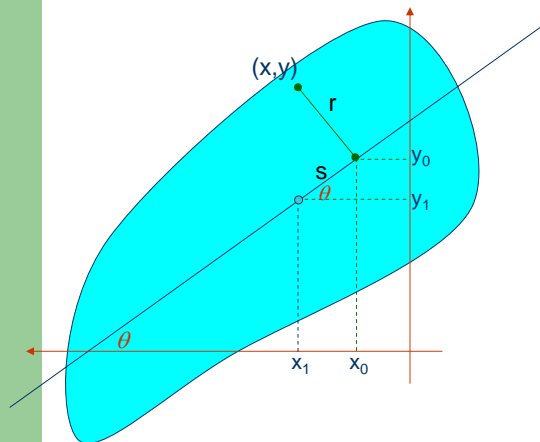


$$x_1 = -\rho \sin \theta$$
$$y_1 = \rho \cos \theta$$

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Recap Region Orientation



$$x_0 = x_1 + s \cos \theta$$

$$y_0 = y_1 + s \sin \theta$$

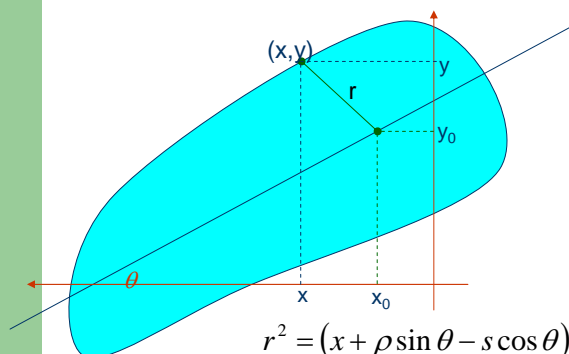
$$x_0 = (-\rho \sin \theta) + s \cos \theta$$

$$y_0 = (\rho \cos \theta) + s \sin \theta$$

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Recap Region Orientation



$$r^2 = (x - x_0)^2 + (y - y_0)^2$$

$$x_0 = (-\rho \sin \theta) + s \cos \theta$$

$$y_0 = (\rho \cos \theta) + s \sin \theta$$

Substitute x_0 and y_0

$$r^2 = (x + \rho \sin \theta - s \cos \theta)^2 + (y - \rho \cos \theta - s \sin \theta)^2$$

$$r^2 = x^2 + y^2 + \rho^2 + s^2 - 2s(x \cos \theta + y \sin \theta) + 2\rho(x \sin \theta - y \cos \theta)$$

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Recap Region Orientation

$$r^2 = x^2 + y^2 + \rho^2 + s^2 - 2s(x \cos \theta + y \sin \theta) + 2\rho(x \sin \theta - y \cos \theta)$$

$$\frac{\partial}{\partial s} r^2 = 2s - 2(x \cos \theta + y \sin \theta)$$

$$s = x \cos \theta + y \sin \theta$$

Substitute s back to r

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Recap Region Orientation

$$r^2 = x^2 + y^2 + \rho^2 + s^2 - 2s(x \cos \theta + y \sin \theta) + 2\rho(x \sin \theta - y \cos \theta)$$

$$r^2 = x^2 + y^2 + \rho^2 - (x \cos \theta + y \sin \theta)^2 + 2\rho(x \sin \theta - y \cos \theta)$$

$$r^2 = x^2 + y^2 + \rho^2 - x^2 \cos^2 \theta - 2xy \sin \theta \cos \theta - y^2 \sin^2 \theta + 2\rho(x \sin \theta - y \cos \theta)$$

$$r^2 = x^2(1 - \cos^2 \theta) + y^2(1 - \sin^2 \theta) - 2xy \sin \theta \cos \theta + 2\rho(x \sin \theta - y \cos \theta) + \rho^2$$

$$r^2 = x^2 \sin^2 \theta + y^2 \cos^2 \theta - 2xy \sin \theta \cos \theta + 2\rho(x \sin \theta + y \cos \theta) + \rho^2$$

$$r^2 = (x \sin \theta - y \cos \theta)^2 + 2\rho(x \sin \theta - y \cos \theta) + \rho^2$$

$$r^2 = (x \sin \theta - y \cos \theta + \rho)^2$$

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Recap Region Orientation

$$\frac{\partial}{\partial \rho} E = \frac{\partial}{\partial \rho} \left(\iint (x \sin \theta - y \cos \theta + \rho)^2 B(x, y) dx dy \right)$$

$$a = x \sin \theta - y \cos \theta$$

$$\frac{\partial}{\partial \rho} r^2 = \frac{\partial}{\partial \rho} \iint (a^2 + 2a\rho + \rho^2) B(x, y) dx dy$$

$$\iint 2aB(x, y) dx dy + \iint 2\rho B(x, y) dx dy = 0$$

$$\sin \theta \iint xB(x, y) dx dy - \cos \theta \iint yB(x, y) dx dy + \rho A = 0$$

$$\rho = -\sin \theta \frac{\iint xB(x, y) dx dy}{A} + \cos \theta \frac{\iint yB(x, y) dx dy}{A}$$

$$\rho = -\bar{x} \sin \theta + \bar{y} \cos \theta$$

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Recap Region Orientation

Substitute ρ back to r

$$E = \iint ((x - \bar{x}) \sin \theta - (y - \bar{y}) \cos \theta)^2 B(x, y) dx dy$$

$$x' = x - \bar{x}, \quad y' = y - \bar{y}$$

$$E = \iint (x' \sin \theta - y' \cos \theta)^2 B(x, y) dx dy$$

$$E = \sin^2 \theta \underbrace{\iint x'^2 B(x, y) dx dy}_a - 2 \sin \theta \cos \theta \underbrace{\iint x' y' B(x, y) dx dy}_b + \cos^2 \theta \underbrace{\iint y'^2 B(x, y) dx dy}_c$$

$$E = a \sin^2 \theta - 2b \sin \theta \cos \theta + c \cos^2 \theta$$

take derivative wrt θ and equating it to 0 \rightarrow

$$\tan 2\theta = \frac{b}{a - c}$$

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Homework from last lecture

- Show that following holds $E_1 = E_2$
where

$$E_1 = a \sin^2 \theta - b \sin \theta \cos \theta + c \cos^2 \theta$$

$$E_2 = \frac{1}{2}(a+c) - \frac{1}{2}(a-c)\cos 2\theta - \frac{1}{2}b \sin 2\theta$$

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Pyramid Representation

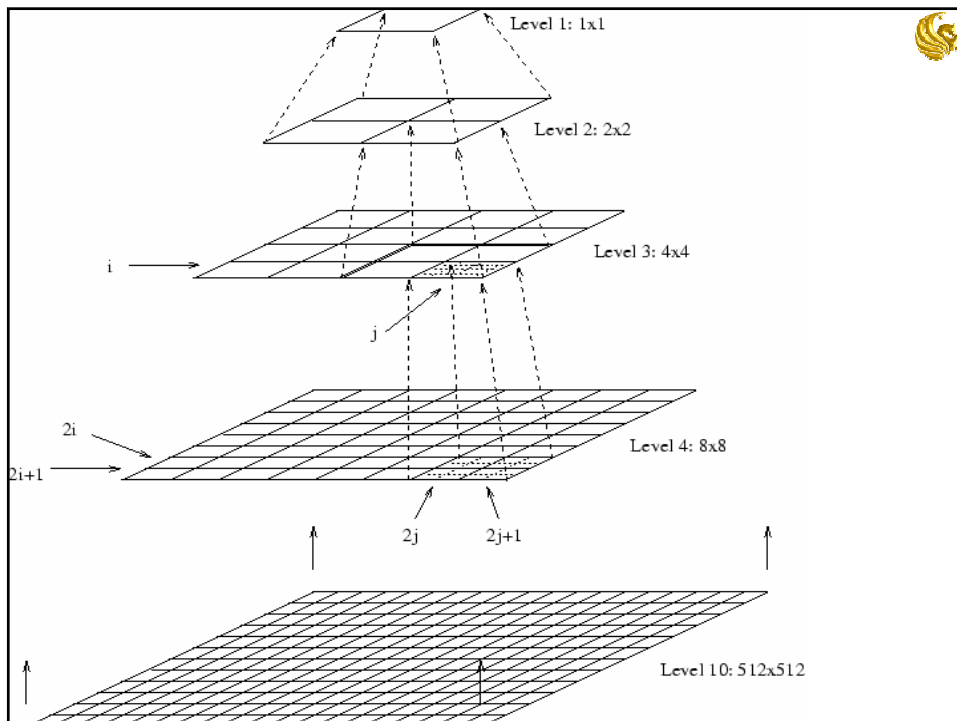
Gaussian
Laplacian

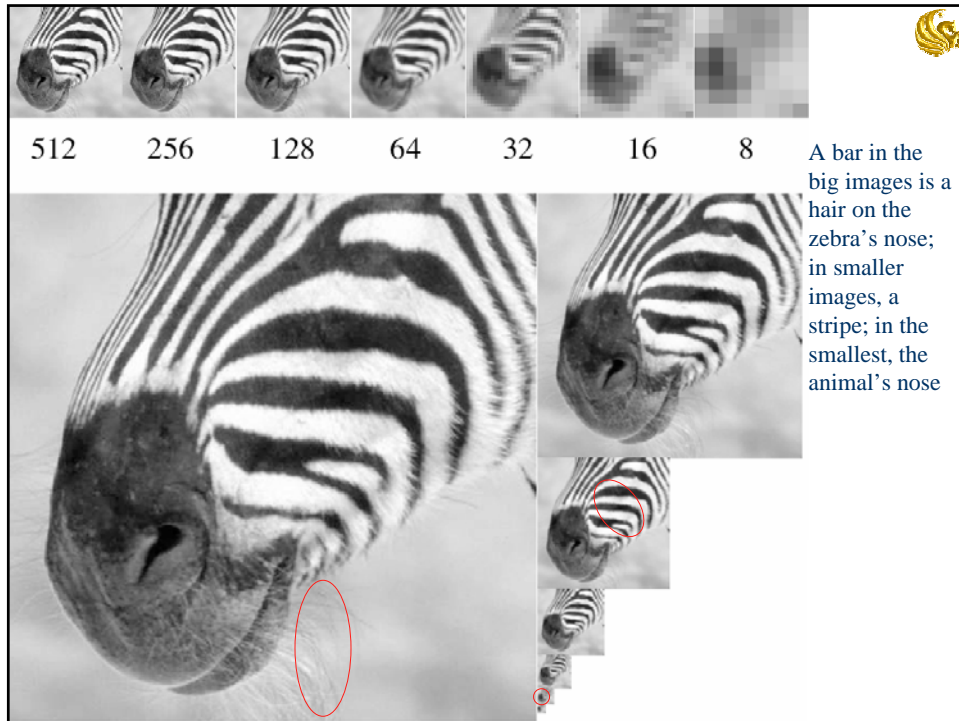
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Gaussian Pyramid

- Very useful for representing images
- Image Pyramid is built by using multiple copies of image at different *scales*.
- Each level in the pyramid is $\frac{1}{4}$ of the size of previous level
- The highest level is of the highest resolution
- The lowest level is of the lowest resolution

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Aliasing Problem

- Can't shrink an image by taking every second pixel
- If we do, characteristic errors appear
 - In the next few slides
 - Typically, small phenomena look bigger; fast phenomena can look slower
 - Common phenomenon
 - Wagon wheels rolling the wrong way in movies
 - Checkerboards misrepresented in ray tracing
 - Striped shirts look funny on color television

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- Resample the checkerboard by taking one sample at each circle. In the case of the top left board, new representation is reasonable.
- Top right also yields a reasonable representation. Bottom left is all black (dubious) and bottom right has checks that are too big.

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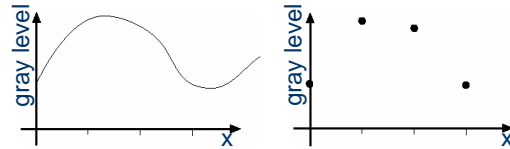
Pyramid With Every Other Pixel

Constructing a pyramid by taking every second pixel leads to layers that badly misrepresent the top layer

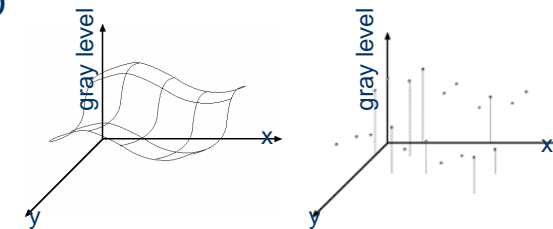


Sampling

- 1D



- 2D



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Smoothing

- High frequencies (edges) lead to trouble with sampling.
- Solution: suppress edges before sampling
- Common solution: use a Gaussian
 - Convolve image with Gaussian filter

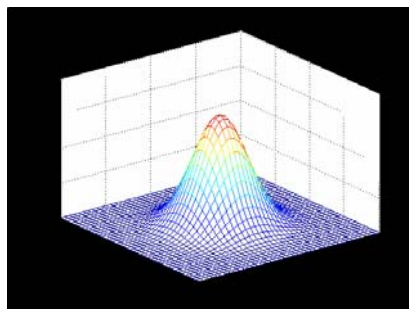
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Gaussian Filter

$$G_{\sigma}(x, y) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{(x^2 + y^2)}{2\sigma^2}\right)$$

- gaussian*gaussian=another gaussian
- Symmetric filter
- gaussians are low pass filters
 - removes noise



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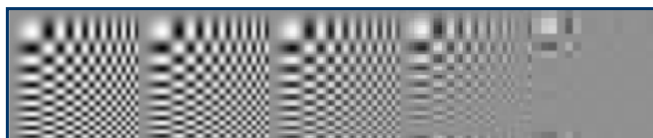


Scaled images

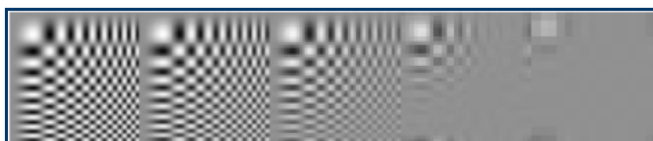
without smoothing



with smoothing
sigma 1 pixel



with smoothing
sigma 1.4 pixel



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Applications of Scaled Images

- Search for correspondence
 - look at coarse scales, then refine with finer scales
- Edge tracking
 - "Good" edge at a fine scale has parents at a coarser scale
- Control of detail and computational cost in matching
 - Finding stripes
 - Very important in texture representation

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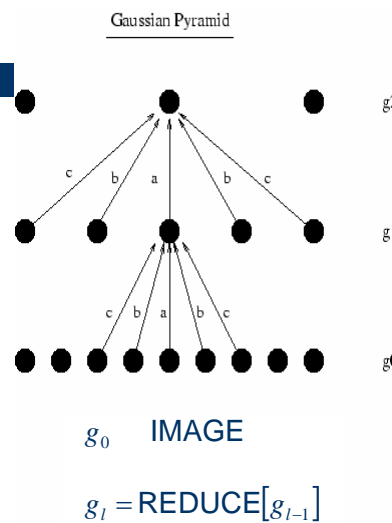
Gaussian Pyramid

- Let w be Gaussian filter

$$g_l(i) = \sum_{m=-2}^2 \hat{w}(m) g_{l+1}(2i+m)$$

$$g_l(2) = \hat{w}(-2)g_{l+1}(4-2) + \hat{w}(-1)g_{l+1}(4-1) + \hat{w}(0)g_{l+1}(4) + \hat{w}(1)g_{l+1}(4+1) + \hat{w}(2)g_{l+1}(4+2)$$

$$g_l(2) = \hat{w}(-2)g_{l+1}(2) + \hat{w}(-1)g_{l+1}(3) + \hat{w}(0)g_{l+1}(4) + \hat{w}(1)g_{l+1}(5) + \hat{w}(2)g_{l+1}(6)$$





Convolution Kernel w

$$[w(-2), w(-1), w(0), w(1), w(2)]$$

- Symmetric

$$w(i) = w(-i) \Rightarrow [c, b, a, b, c]$$

- Sum must be 1

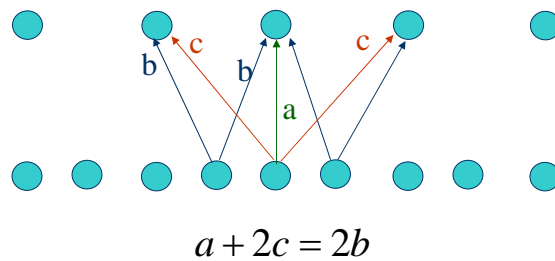
$$a + 2b + 2c = 1$$

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Reduce 1D Convolution Kernel w

- All nodes at a given level must contribute the same total weight to the nodes at the next higher level



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Convolution Kernel (5x1)

$$w(0) = a$$

$$w(-1) = w(1) = \frac{1}{4}$$

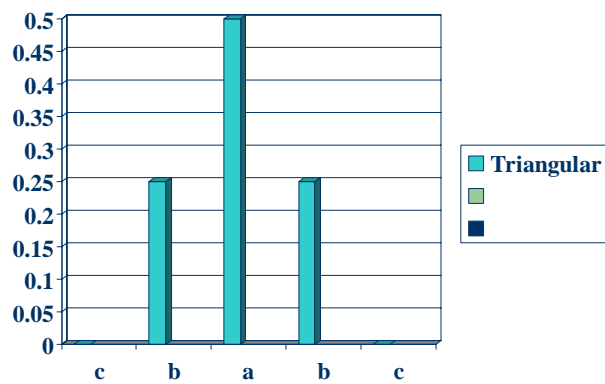
$$w(-2) = w(2) = \frac{1}{4} - \frac{a}{2}$$

a=0.4 GAUSSIAN
a=0.5 TRIANGULAR

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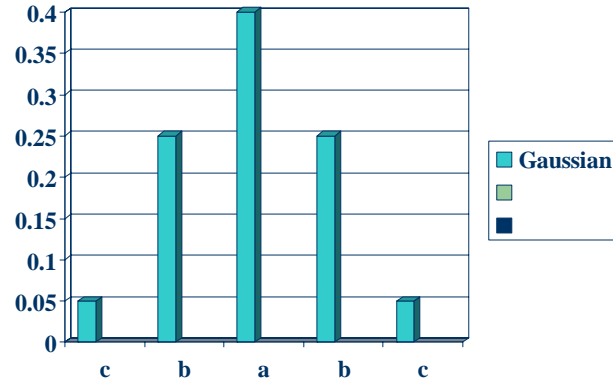
Triangular (5x1)



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Approximate Gaussian (5x1)



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Two Dimensions?

- Gaussian is separable

$$\hat{I}(x, y) = I(x, y) * G(x, y)$$

$$\hat{I}(x, y) = I(x, y) * G(x) * G(y)$$

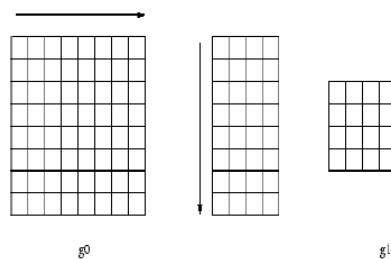
$$G(x) = G^T(y) \text{ transpose}$$

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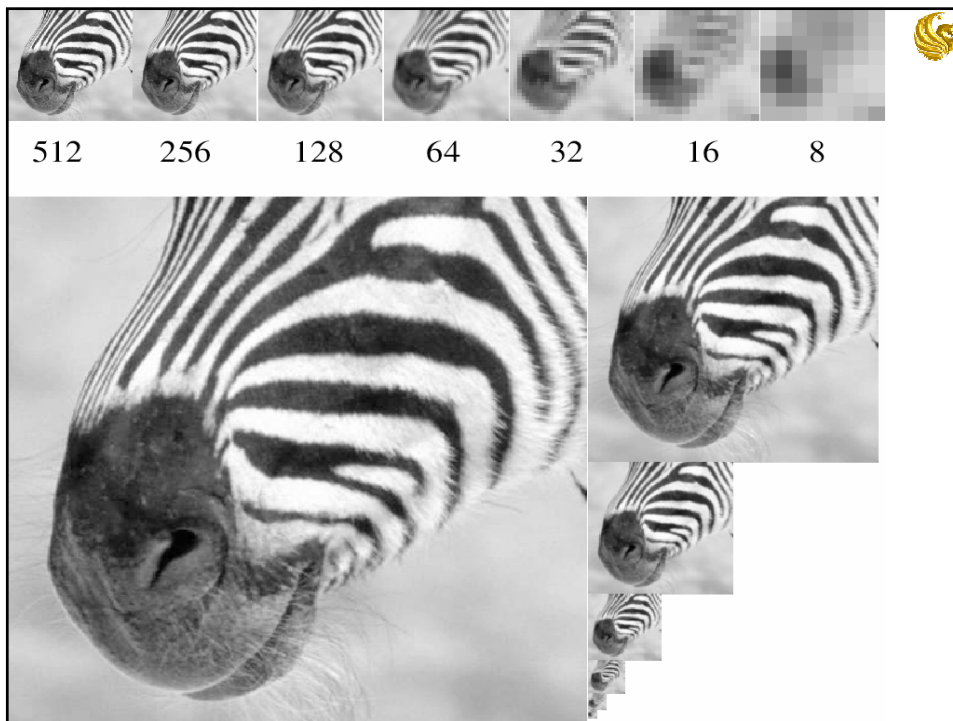


Gaussian Pyramid Algorithm

- Apply 1D mask to alternate pixels along each row of image.
- Apply 1D mask to alternate pixels along each column of resulting image from previous step.



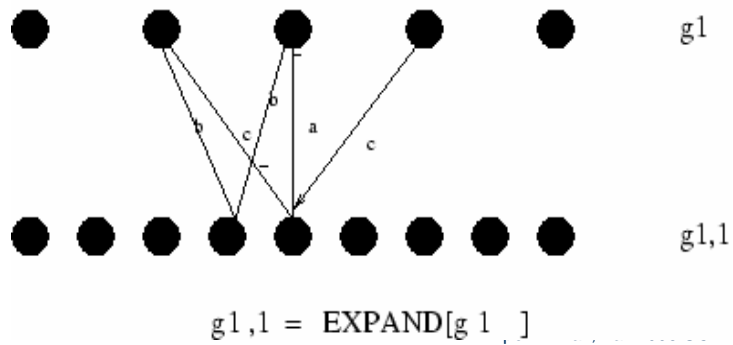
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Expand 1D

Gaussian Pyramid



Expand 1D

$$g_{l,n}(i) = \sum_{p=-2}^2 \hat{w}(p) g_{l,n-1}\left(\frac{i-p}{2}\right)$$

$$g_{l,n}(4) = \hat{w}(-2) g_{l,n-1}\left(\frac{4-2}{2}\right) + \hat{w}(-1) g_{l,n-1}\left(\frac{4-1}{2}\right) + \hat{w}(0) g_{l,n-1}\left(\frac{4}{2}\right) + \hat{w}(1) g_{l,n-1}\left(\frac{4+1}{2}\right) + \hat{w}(2) g_{l,n-1}\left(\frac{4+2}{2}\right)$$

$$g_{l,n}(4) = \hat{w}(-2) g_{l,n-1}(1) + \hat{w}(0) g_{l,n-1}(2) + \hat{w}(2) g_{l,n-1}(3)$$



Expand 1D

$$g_{l,n}(i) = \sum_{m=-2}^2 \hat{w}(p) g_{l,n-1}\left(\frac{i-p}{2}\right)$$

$$g_{l,n}(3) = \hat{w}(-2)g_{l,n-1}\left(\frac{3-2}{2}\right) + \hat{w}(-1)g_{l,n-1}\left(\frac{3-1}{2}\right) + \\ \hat{w}(0)g_{l,n-1}\left(\frac{3}{2}\right) + \hat{w}(1)g_{l,n-1}\left(\frac{3+1}{2}\right) + \hat{w}(2)g_{l,n-1}\left(\frac{3+2}{2}\right)$$

$$g_{l,n}(3) = \hat{w}(-1)g_{l,n-1}(1) + \hat{w}(1)g_{l,n-1}(2)$$

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The Laplacian Pyramid

- Similar to edge detected images
- Most pixels are zero
- Can be used in image compression

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Constructing Laplacian Pyramid

- Compute Gaussian pyramid

$$g_k, g_{k-1}, g_{k-2}, \dots, g_2, g_1$$

- Compute Laplacian pyramid as follows:

$$L_k = g_k - \text{EXPAND}(g_{k-1})$$

$$L_{k-1} = g_{k-1} - \text{EXPAND}(g_{k-2})$$

$$L_{k-2} = g_{k-2} - \text{EXPAND}(g_{k-3})$$

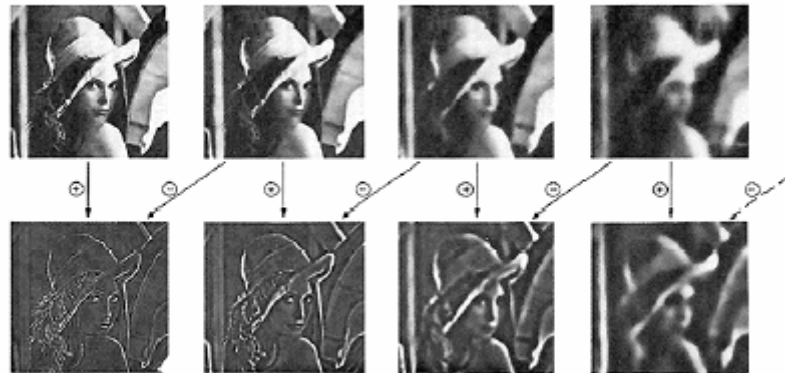
⋮

$$L_1 = g_1$$

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Laplacian Pyramid





Reconstructing Image

$$\begin{aligned}
 g_1 &= L_1 \\
 g_2 &= EXPAND(g_1) + L_2 \\
 g_3 &= EXPAND(g_2) + L_3 \\
 &\vdots \\
 g_k &= EXPAND(g_{k-1}) + L_k
 \end{aligned}$$

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The Laplacian Pyramid

- Synthesis (Coding)
 - Compute Gaussian pyramid
 - Compute Laplacian pyramid

- Analysis (Decoding)
 - Compute Gaussian pyramid from Laplacian pyramid
 - g_1 is reconstructed image

$$L_1 = g_1 - EXPAND[g_2]$$

$$L_2 = g_2 - EXPAND[g_3]$$

$$L_3 = g_3 - EXPAND[g_4]$$

$$L_4 = g_4$$

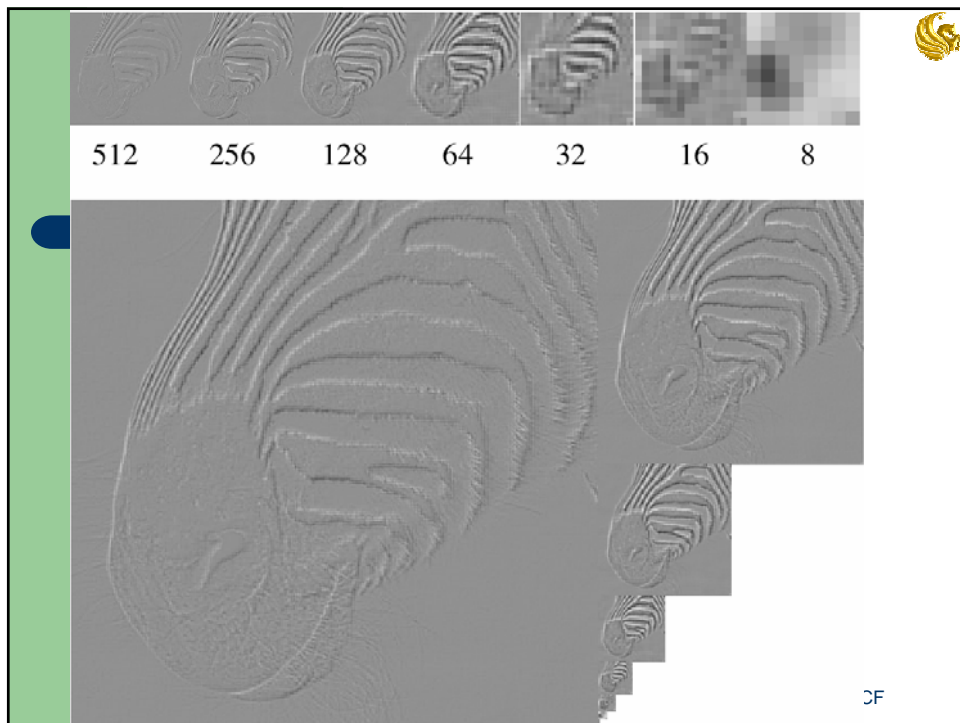
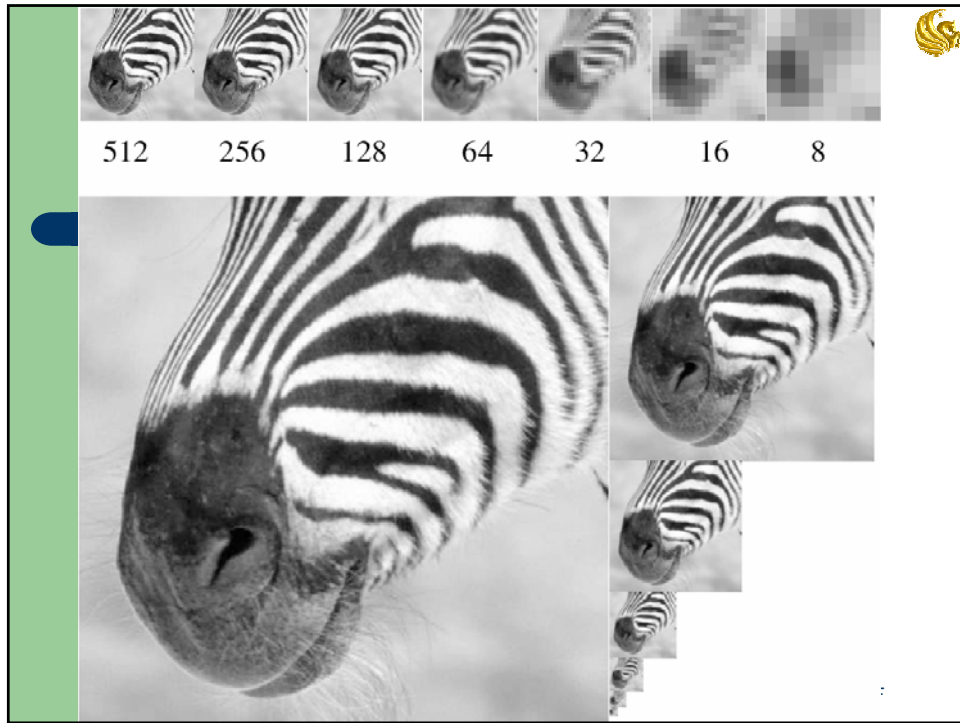
$$g_4 = L_4$$

$$g_3 = EXPAND[g_4] + L_3$$

$$g_2 = EXPAND[g_3] + L_2$$

$$g_1 = EXPAND[g_2] + L_1$$

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Programming Assignment

- Write the Gaussian Pyramid algorithm
 - The algorithm should be capable of providing any number of resolutions
 - Report should include scaled images of the Lenna image.
 - Due 12 October, 2005

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